# TECHNICAL REPORT

## THEORETICAL PREDICTION OF THE FLOW IN THE WAKE OF A HELICOPTER ROTOR

PART 2 - FORMULATION AND APPLICATION OF THE ROTOR-WAKE-FLOW COMPUTER PROGRAM

By: Peter Crimi

CAL No. BB-1994-S-2

Prepared for:

U.S. Army Ballistic Research Laboratories Aberdeen Proving Ground, Maryland 21005

Final Report - Part 2 Contract No. DA30-069-AMC-645(R) September 1965

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#### SUMMARY

As part of a study carried out at Cornell Aeronautical Laboratory for the U. S. Army (Contract No. DA-30-069-AMC-645(R)), two digital computer programs were prepared which direct the calculation of the time-varying flow in the vicinity of a helicopter rotor in forward or hovering flight. Fuselage interference effects are taken into account. The applicability of these programs to specific problems and procedures for their use are the subjects treated here.

First, the assumptions made in constructing the mathematical model and the relationship of the model to the physical flow are outlined. In this connection, the assumptions necessary for numerical analysis and the functional structure of the programs are also given.

Then, the formulations which were coded are presented. Included in the formulations are the coordinate identifications used and the definitions of program variables.

Finally, the procedures for implementation of the programs are given. The relationship of input quantities to aircraft flight parameters, program accuracy and computer running time are specified. A sample calculation, including both inputs and outputs, is presented. Program listings and operational information related to the programs are given in appendices.

#### FOREWORD

The work reported herein, performed between September 1964 and September 1965, was accomplished by the Cornell Aeronautical Laboratory, Inc. (CAL), Buffalo, New York for the Director of Ballistic Research Laboratories, (BRL) Aberdeen Proving Ground, Maryland. The research effort was performed under Contract DA 30-069-AMC-645(R) and was monitored for BRL by Mr. Thomas Coyle as Technical Supervisor. Dr. Peter Crimi of CAL conducted the study and received assistance from Mr. Alexander Sowydra during the development of the mathematical model and Mr. Harvey Selib for the digital computer programming.

This document is Part 2 of the final report under the contract. It describes the formulation and application of the rotor-wake flow computer program and is of use primarily to those who plan to use the digital computing program. Part 1 of the final report describes the development of the theory, discusses the results of the computation, and provides a comprehensive discussion of the work performed under the contract.

CAL Report Numbers have been assigned as follows:

BB-1994-S-1, THEORETICAL PREDICTION OF THE FLOW IN THE WAKE OF A HELICOPTER ROTOR, Part 1 - Development of Theory and Results of Computations

BB-1994-S-2, THEORETICAL PREDICTION OF THE FLOW IN THE WAKE OF A HELICOPTER ROTOR, Part 2 - Formulation and Application of the Rotor Wake Flow Computer Programs

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#### 1. INTRODUCTION

A study was carried out at Cornell Aeronautical Laboratory for the U. S. Army (Contract No. DA 30-069-AMC-645(R)) with the objective of developing a theory for the prediction of the flow field in the wake of a helicopter rotor. As a part of this study, two digital computer programs were prepared which incorporate the analytical models derived. Given the flight conditions and geometric configuration of the aircraft, the programs direct the computation of the time-varying flow at arbitrary points in the wake of a translating rotor. Account is taken of fuselage interference effects.

This report is intended to provide the information which would be of use to technical personnel who have need of the data which these programs supply. An outline of the mathematical models used, the major simplifying assumptions applied and the relationship of the mathematical model to the physical flow are given so that the user may determine the applicability of the program to his particular problem. In addition, the equations which were coded are given and the necessary inputs are listed together with their relationship to flight conditions and their effect on running time and overall accuracy. The latter information will allow the user to convey to a computer programmer sufficient data to implement the programs in the manner desired.

No attempt has been made here to present rigorous derivations or complete justifications for the formulations given and assumptions made. The intention rather is only to provide sufficient information concerning the model so that its limitations and applicability are made clear. The complete derivation of the theory which the computer programs implement is reported in Reference 1.

The information necessary for the physical operation of the programs is given in Appendices I and II. Included there are program restrictions, usage, data preparation, and coding information.

#### 2. THE MATHEMATICAL MODEL

#### DISCUSSION OF THE PHYSICAL FLOW

It is desired to define analytically the flow in the vicinity of a helicopter in translational or hovering flight out of ground effect. Consideration is limited to craft having a single rotor with from one to four blades.

There are three primary contributions to the flow at a given point relative to the aircraft. Specifically, the rotor blades, the wake of the rotor blades, and the fuselage all affect the air velocity. These three effects are interrelated in a highly nonlinear manner. The lifting blades induce a flow on their wake, causing the wake to distort. The distorted wake induces a flow on the blades, altering their loading, the two combine to affect the flow about the fuselage, and the fuselage in turn affects the blade loading and wake displacement.

The blades may be regarded as wings of very high aspect ratio in a free stream which is varying harmonically in time. The wake is generated by the blades as a thin sheet of vortical fluid. This sheet has been observed to roll up very rapidly into a pair of vortices (see Reference 2) so that except for the region a few chord-lengths behind the blade, it appears that each blade has trailing from it two vortices, one from the vicinity of the tip and one from the root. Smoke pictures (Reference 2) and the results of an analytical treatment of the wake of a hovering rotor (Reference 3) indicate that the root vortices are rapidly swept up through the center of the rotor plane and then dissipated. The root vortices, therefore, contribute very little to the flow. The smoke pictures also indicate that the tip vortices are quite stable and experience very little viscous dissipation, sustaining themselves for several rotor revolutions.

From the point of view of the fuselage and/or any nonlifting appendages, the flow appears as the superposition of a steady free stream caused by the translation of the aircraft and the periodic flow induced by the rotor and its wake. The contribution of the fuselage to the flow at any point is essentially that due to a body of complicated geometry in unsteady potential flow.

#### THE MODEL FOR THE ROTOR

A wing of high aspect ratio may be mathematically represented, to a very good approximation, by a line vortex with a spanwise variation of circulation such as to produce the proper variation of lift in the spanwise direction (see, for example, Reference 4). Each rotor blade has, therefore, been replaced by a line vortex with one end located at the position of the rotor hub and the other at the position of the blade tip. It has been assumed in adopting this model that the fluid is inviscid and incompressible. This assumption has also been made in formulating the models for the wake and fuselage.

A rigorous treatment of the blade effects would include the specification of radial and azimuthal variation of the circulation about these blade vortices in terms of the blade geometry, the blade motions, and the flow induced by the wake and fuselage. However, it is known a priori that the circulation does not vary substantially in the radial direction and that it varies azimuthally in such a way as to provide nearly a constant lift. Insofar as the blades affect the flow, then, they may be well represented by varying the circulation sinusoidally so as to produce nearly a constant lift and by taking the circulation as constant in the radial direction. This representation of the rotor has been adopted, with the total lift produced by the vortices made to equal the weight of the aircraft.

#### THE MODEL FOR THE WAKE

Since the wake of a rotor has been observed to consist primarily of vortices emanating from near the tip of each blade, the wake is represented by potential vortices, one originating from the tip of each blade vortex, which terminate at some arbitrary point far downstream. The circulation about a wake vortex in the physical flow at any given point is simply related to the circulation about the blade when it generated that portion of the wake. Consistent with that relationship, the circulation about the model of a wake vortex at any point is prescribed to be that which the vortex representing the blade had when it produced that wake element.

As a segment of a wake vortex is generated at the tip of a blade vortex when the blade vortex rotates and translates, a corresponding segment is discarded at the downstream end of the vortex. In this manner, the program is not encumbered by a wake of ever increasing size, while the essential structure of the wake is retained.

It should be noted that the positions of the wake vortices are not known a priori. The positioning of the wake is a function of the spatial and azimuthal variations of the flow, which in turn depend on the wake geometry itself. The location of the wake vortices, in fact, constitutes the primary function of the program. Once the wake has been located, at a given instant, the flow at any arbitrary point is completely defined and may be computed in a straightforward manner.

An enormous simplification would, of course, result if the wake geometry were prescribed by using some plausible assumption. This, in fact, has been done in a number of analyses and useful results obtained. For example, the time-varying flow in the rotor plane (Reference 5) and an indication of the spatial distribution of the time-average of the downwash (Reference 6) have been obtained in this manner. However, this program has as its objective the accurate prediction of the time-varying flow at arbitrary locations in the vicinity of the aircraft; wake distortions are a major factor in defining this flow, and can neither be neglected nor assumed known without introducing unacceptably large errors.

Also, it should be noted that the wake vortices must be assumed to have a small but finite core of rotational fluid (which, in fact, a physical vortex must have) even though the flow external to this core is precisely that due to a simple potential vortex having an infinite velocity at its center. This assumption is necessary because, if the wake is to be allowed to convect under its own influence, then the effect of immediately adjacent wake elements on a wake vortex must be computed. If a simple potential representation were used, infinite velocities of convection would then be predicted throughout the wake. On the other hand, the so called self-induced (i.e., locally induced)

fluid velocity acting on a finite-core vortex may be obtained in terms of the local curvature of the vortex and its core radius. The expressions for this velocity have been incorporated in the program.

The size of the core of a physical vortex is related to the kinetic energy in the flow. This relationship may be utilized to provide a rational means for computing the core size of the wake vortices for the model. This was done, and computations were performed which revealed that core size is relatively insensitive to flight conditions or blade azimuth and that a value for core radius of five percent of a rotor radius may be utilized for all flight conditions without introducing significant errors.

Core size may change significantly due to stretching of wake vortices; the volume of the rotational core must remain constant in an inviscid flow. This effect has been taken into account in the formulation.

#### THE MODEL FOR THE FUSELAGE

The fuselage is represented as though it were immersed in a uniform free stream of constant magnitude and direction. The assumed free stream consists of two components, one being the negative of the velocity of translation of the aircraft, and the other being a time and spatial average of the downwash induced by the rotor and its wake. The latter component may be computed by temporarily omitting the fuselage representation from the program and evaluating the desired averages where the fuselage is located.

At high forward speed, the time and spacial variations of the stream experienced by the fuselage are small, and so may be neglected without causing large errors. At low forward speed the flow over the fuselage does vary substantially, but the total effect of the fuselage is then small in comparison with wake and rotor-induced effects, and so the error is again not appreciable.

Since, in general, the geometry of a helicopter fuselage cannot be adequately described analytically, neither can the flow about the fuselage be represented in simple closed form. However, assuming that the fluid is both incompressible

and inviscid, which it very nearly is, the potential flow about a nonlifting body may always be represented by replacing the body by a surface distribution of potential sources having spacially varying strength (see Reference 7). This representation has been used to compute the effect of the fuselage on the flow.

#### ASSUMPTIONS FOR NUMERICAL ANALYSIS

The models of the rotor blades, the wake, and the fuselage described above may, at least in general terms, be formulated as continuous functions of time and spacial coordinates. A digital computer cannot, of course, continuously integrate continuous functions. Therefore, step-wise and interpolative approximations have been made.

A rectangular integration scheme is used in performing integrations in time. That is, when integrating velocity to compute displacement, the velocity is assumed to remain constant over an interval of time corresponding to a small finite change in the azimuth position of the blades.

Spacial integrations over the wake vortices are performed by assuming that these vortices are made up of small rectilinear vortex segments whose circulation is constant from one end point to the next. The position of the wake is then defined by the locations of the end points of these segments. Consistent with the approximation made in the time integration, the initial length of each wake segment is the length of the arc swept out by the blade tip over the interval used for time integration. Self-induced effects at a given wake point are computed by taking, as the local curvature, the reciprocal of the radius of the circle passing through the wake point in question and the two wake points adjacent to it.

The surface of the fuselage has been replaced by a set of plane quadrilateral source sheets. The source strength per unit area for a given sheet is assumed to be uniform over the sheet. The determination of these strengths may be separated from the actual computation of the flow, and is accomplished

with a separate computer program. The output of the latter program then forms part of the input to the main program.

#### FUNCTIONAL STRUCTURE OF THE PROGRAMS

#### The Main Program

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The program modeling the rotor, the wake and the fuselage has been constructed to form a numerical analogue to the physical flow. Given an initial wake geometry and aircraft flight conditions, it proceeds to integrate in time, convecting the wake according to the analytical prescriptions described above. The process will continue through as many rotor revolutions as desired. It has been found that generally a periodic flow is eventually established after which, of course, no further information can be obtained by continuing the computations. A criterion has been found for choosing a number of rotor revolutions sufficient for the establishment of a periodic flow. This criterion is given in the discussion of program implementation.

As the computations proceed, the wake configuration, as well as fluid velocities at any points desired, at a given instant (i. e., azimuth position) are stored on tape. This information is relinquished as output upon completion of computations.

The flow of information as computations proceed is represented schematically in Figure 1.

#### The Supplemental Fuselage Program

As noted previously, the function of the supplemental fuselage program is to determine the strengths of the source sheets representing the fuselage. The procedure used is based on the method reported in Reference 8. The program is given the locations of the quadrilaterals representing the fuselage surface. It is then required that the combined effer as of the free stream and the sum of source-induced velocities be such that the fluid velocity normal to each element be zero. This requirement provides a set of linear algebraic

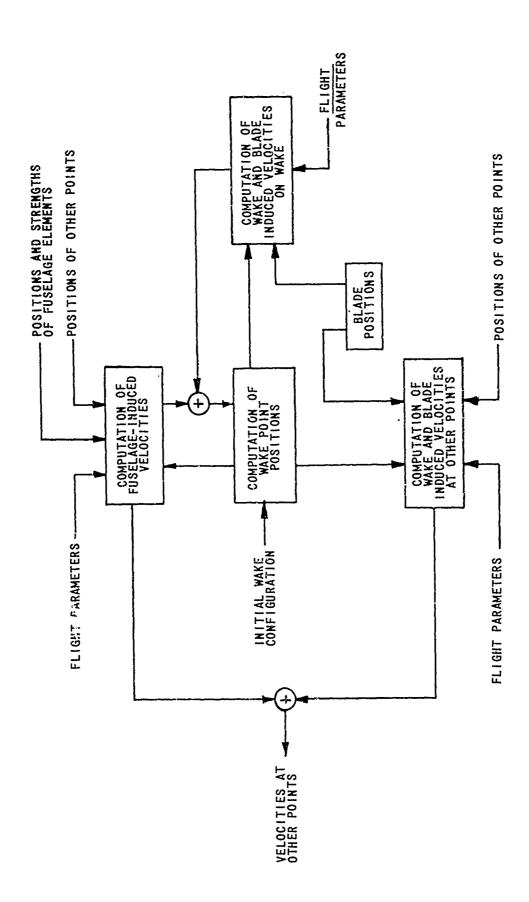


Figure I SCHEMATIC DIAGRAM OF THE FLOW OF INFORMATION FOURTHE MAIN PROGRAM

Table 1

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No.

equations with the source strengths as unknowns. The fuselage program computes the coefficients for this set of equations and then solves them, using a simple iterative procedure. The strengths and related geometric parameters are the outputs, which are then used as inputs to the main program.

#### 3. FORMULATIONS FOR THE MAIN PROGRAM

In the following sections, the equations are given which were coded for the main program. All distances have been nondimensionalized by rotor radius R and velocities by rotor tip speed  $\Omega R$ , where  $\Omega$  is the angular velocity of the rotor.

#### COORDINATE IDENTIFICATIONS AND NOMENCLATURE

#### Rotor and Rotor Wake

A coordinate system fixed in the tip-path-plane of the rotor is used. The model for a two-bladed rotor and its wake is shown in Figure 2. As noted on the figure, a free stream of dimensionless magnitude  $\mu$  is directed at an angle  $\alpha_r$  to the tip-path-plane and parallel to the x-3 plane. The azimuth position  $\psi$  of the rotor is defined to be the angle between blade vortex 1 and the x-axis, as shown (blade numbers increase in a counterclockwise direction when the rotor is viewed from above). The points  $P_{ij}$  are the wake reference points; the first subscript, i, increases successively proceeding down the wake vortex for a given blade, and the second subscript, j, denotes the number of the blade which generated that wake vortex. Each wake segment is associated with that end point having the lower first subscript. For example, the element between points  $P_{22}$  and  $P_{32}$  is denoted as element (2, 2). Each element (i,j) is assigned a dimensionless core radius  $a_{ij}$  and strength  $P_{ij}$ . For convenience in computation, the latter quantity has been normalized by the average circulation about the blade vortices.

BLADE VORTEX 2

P12

P32

P32

BLADE VORTEX 1

Figure 2 MODEL FOR THE ROTOR AND WAKE

### Fuselage

The model of the fuselage is referred to the same coordinate system as is that of the rotor and its wake. The surface representing the fuselage is shown schematically in Figure 3, with a few representative source-sheet elements outlined.

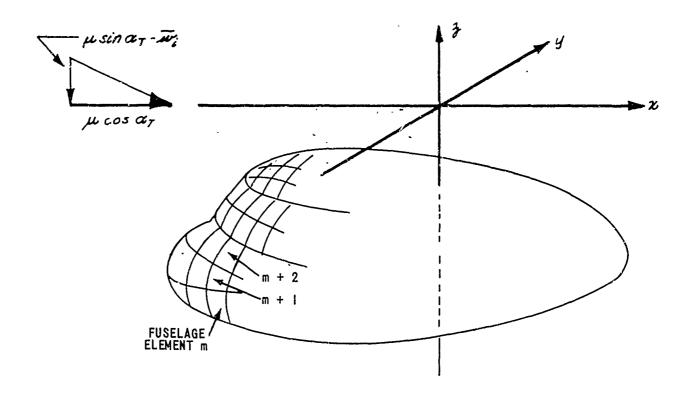


Figure 3 SCHEMATIC REPRESENTATION OF FUSELAGE MODEL

The fuselage is assumed to be subjected to a uniform free stream with  $\varkappa$ -component  $\mu \cos \alpha_r$  and 3-component  $\overline{\omega_i} - \mu \sin \alpha_r$ , where  $\overline{\omega_i}$  is a time and spacial average of rotor and wake-induced velocities acting on the fuselage in the 3-direction. The fuselage has been assumed to be symmetric about the z-3 plane, so that only half of the fuselage need be considered. The source elements are numbered consecutively from m=1 to  $m=N_f$ , where  $N_f$  is the number of fuselage elements representing (half of) the fuselage. Each fuselage element has its vertices numbered (from one to four) in clockwise fashion when viewed from the exterior of the fuselage.

Associated with each fuselage element m are the normalized source strengths  $\sigma_{\tilde{\chi}_m}$  and  $\sigma_{\tilde{\chi}_m}$ . The total source strength of element m is thus

$$\mu \cos \alpha_T \sigma_{z_m} + (\overline{w_i} - \mu \sin \alpha_T) \sigma_{z_m}$$

The quantities  $\sigma_{m}$  and  $\sigma_{m}$  are computed by the supplemental fuselage program, as described in Formulations For The Supplementary Fuselage Program. Certain other quantities are also obtained from the supplemental fuselage program and used as inputs to the main program. These quantities define the position and orientation of the elements. Their definitions are given in Formulations For The Supplementary Fuselage Program.

#### EQUATIONS FOR COMPUTING DISPLACEMENTS AND VELOCITIES

#### General Equations

Let  $v_{\chi}(x, y, y, y), v_{y}(x, y, y, \psi)$  and  $v_{\chi}(x, y, y, y, \psi)$  denote the dimensionless components of fluid velocity at point (x, y, y) for the rotor at azimuth position  $\psi$ . Then if  $(x_{ij}, y_{ij}, y_{ij})$  denote the coordinates of vortex end point  $P_{ij}$ , the wake displacement is given by

$$x_{ij}(\psi + \Delta \psi) = x_{i-1,j}(\psi) + v_{x}(x_{i-1,j}, y_{i-1,j}, y_{i-1,j}, \psi) \Delta \psi 
y_{i,j}(\psi + \Delta \psi) = y_{i-1,j}(\psi) + v_{y}(x_{i-1,j}, y_{i-1,j}, y_{i-1,j}, \psi) \Delta \psi 
y_{i,j}(\psi + \Delta \psi) = y_{i-1,j}(\psi) + v_{x}(x_{i-1,j}, y_{i-1,j}, y_{i-1,j}, \psi) \Delta \psi$$
(1)

for

$$i = 2, 3, \cdots, N_W + 1$$

and

$$j=1,2,\cdots,N_B$$
.

The integers  $N_{\mathcal{B}}$  and  $N_{\mathcal{W}}$  denote, respectively, the number of blades and the number of wake elements per blade included in the calculation, and  $\Delta \Psi$  is the incremental change in blade azimuth position:

$$\Delta \psi = \frac{2\pi}{N_A}$$

$$N_W = N_R N_A$$

where  $N_A$  is an integer, being the number of azimuth stations into which the rotor plane is divided, and  $N_R$  is the number of revolutions of wake per blade taken into account.

The wake and blade reference points not determined through equations (1), namely  $P_{0j}$  and  $P_{tj}$ , are simply located according to

$$x_{oj}(\psi) = y_{oj}(\psi) = 3o_{j}(\psi) = 0$$

$$x_{ij}(\psi) = \cos\left[\psi + \frac{2\pi}{N_B}(j-1)\right]$$

$$y_{1j}(\psi) = \sin\left[\psi + \frac{2\pi}{N_B}(j-1)\right]$$

$$3i_{j}(\psi) = 0$$
(2)

for

$$j = 1, 2, \cdots, N_B$$
.

The fluid velocity components at a point (2,4,3) needed in Equations (1) and in the definition of the flow at an arbitrary point, may be broken down as follows:

$$\frac{1}{\lambda} V_{\chi}(x,y,3) = V_{\chi}(x,y,3) = \frac{\mu}{\lambda} \cos \alpha_T + V_{\omega_{\chi}}(x,y,3) + V_{f_{\chi}}(x,y,3)$$

Thought a series and a series

$$\frac{1}{\lambda} v_{y}(x,y,3) = V_{y}(x,y,3) = V_{w_{y}}(x,y,3) + V_{f_{y}}(x,y,3)$$
(3)

$$\frac{1}{\lambda} v_3(x,y,3) = V_3(x,y,3) = -\frac{\mu}{\lambda} \sin \alpha_7 + V_{w_3}(x,y,3) + V_{f_3}(x,y,3)$$

where  $\lambda$  is an input parameter which relates directly to the thrust on the rotor (see Procedure For Implementation Of The Programs),  $V_{\omega_{\chi}}$ ,  $V_{\omega_{\chi}}$  and  $V_{\omega_{\chi}}$  are the contributions of the wake and blade vortices and  $V_{f_{\chi}}$ ,  $V_{f_{\chi}}$  and  $V_{f_{\chi}}$  are the contributions of the fuselage source sheets.

The strengths and core sizes of the wake elements for azimuth position  $\psi_{+\Delta}\psi$  are assigned in terms of inputs and their values at azimuth position  $\psi$ . Specifically, the strengths are given by

$$\Gamma_{ij}(\psi + \Delta \psi) = \Gamma_{i-1,j}(\psi), \qquad \begin{cases} i = 2, 3, \dots, N_{W} \\ j = 1, 2, \dots, N_{B} \end{cases}$$

$$\Gamma_{1j}(\psi + \Delta \psi) = \frac{1}{2} \left[ \Gamma_{B_{i}}(\psi) + \Gamma_{B_{j}}(\psi + \Delta \psi) \right], \quad j = 1, 2, \dots, N_{B}$$

$$(4)$$

where  $\Gamma_{Bj}$  is the strength of blade element j. The strength of blade element 1 at each azimuth is specified as an input, while

$$\Gamma_{\mathcal{B}_{j}}(\psi) = \Gamma_{\mathcal{B}_{j}}\left[\psi+(j-1)\frac{2\pi}{N_{\mathcal{B}}}\right], \qquad j=2,3,\cdots,N_{\mathcal{B}}$$
 (5)

and, of course,

$$\Gamma_{\mathcal{B}_{j}}(\psi+2\pi) = \Gamma_{\mathcal{B}_{j}}(\psi).$$

The core sizes are assigned according to

$$a_{ij} (\psi + \Delta \psi) = \left[ \frac{L_{i-1,j}(\psi)}{L_{ij}(\psi + \Delta \psi)} \right]^{1/2} a_{i-1,j}(\psi)$$
for
$$j = 1, 2, \dots, N_B.$$
(6)

where  $L_{ij}$  is the length of wake element (i,j):

$$\Delta_{ij} = \left[ \left( x_{i+1,j} - x_{ij} \right)^2 + \left( y_{i+1,j} - y_{ij} \right)^2 + \left( y_{i+1,j} - y_{ij} \right)^2 + \left( y_{i+1,j} - y_{ij} \right)^2 \right]^{\frac{1}{2}}$$
 (7)

The value for  $a_{ij}(\psi)$ ,  $j = 1, 2, ..., N_B$ , are assigned as inputs.

### Effect of Rotor and Wake

The velocity components induced by the blade and wake vortex elements may be represented by the following relations. Define  $q_{x_{i,j}}$ ,  $q_{y_{i,j}}$  and  $q_{y_{i,j}}$  by

$$g_{x_{ij}} = \nu_x G$$

$$g_{y_{ij}} = \nu_y G$$

$$g_{\bar{x}_{ij}} = \nu_{\bar{y}} G$$

$$g_{\bar{x}_{ij}} = \nu_{\bar{y}} G$$
(8)

where

Then, if point (x,y,y) does not lie on a vortex (i.e., is not a wake reference point), wake-induced and blade-induced velocity components are given by

$$V_{x_{w}}(x,y,3) = \sum_{i=0}^{N_{w}} \sum_{j=1}^{N_{g}} q_{x_{ij}}(x,y,3)$$

$$V_{y_{w}}(x,y,3) = \sum_{i=0}^{N_{w}} \sum_{j=1}^{N_{g}} q_{y_{ij}}(x,y,3)$$

$$V_{3_{w}}(x,y,3) = \sum_{i=0}^{N_{w}} \sum_{j=1}^{N_{g}} q_{3_{ij}}(x,y,3)$$

$$(9)$$

If the point in question is a wake reference point, say  $P_{rs}$ , then

$$V_{x_{w}}(x_{rs}, y_{rs}, z_{rs}) = \sum_{i=0}^{N_{w}} \sum_{\substack{j=1\\j\neq s}}^{N_{w}} q_{x_{ij}}(x_{rs}, y_{rs}, z_{rs})$$

$$+ \sum_{i=0}^{N_{w}} q_{x_{is}}(x_{rs}, y_{rs}, z_{rs}) + q_{s_{x}}(x_{rs}, y_{rs}, z_{rs})$$

$$i = 0$$

$$i \neq r-1, r$$
(10)

and similarly for  $V_{y_{\infty}}$  and  $V_{y_{\infty}}$ . The functions  $g_{s_{x}}, g_{s_{y}}$  and  $g_{s_{x}}$  account for self-induced effects. If r > 1, these functions are given by

$$\begin{aligned}
Q_{S_{\mathcal{X}}}(x_{rs}, y_{rs}, y_{rs}) &= m_{\mathcal{X}} \tilde{\mathcal{F}} \\
Q_{S_{\mathcal{Y}}}(x_{rs}, y_{rs}, y_{rs}) &= m_{\mathcal{Y}} \tilde{\mathcal{F}} \\
Q_{S_{\mathcal{X}}}(x_{rs}, y_{rs}, y_{rs}) &= m_{\mathcal{X}} \tilde{\mathcal{F}}
\end{aligned} \tag{11}$$

where

$$m_{\chi} = (y_{r-1,s} - y_{rs})(y_{rs} - y_{r+1,s}) - (y_{rs} - y_{r+1,s})(y_{r-1,s} - y_{rs})$$

$$m_{y} = (y_{r-1,s} - y_{rs})(x_{rs} - x_{r+1,s}) - (y_{rs} - y_{r+1,s})(x_{r-1,s} - x_{rs})$$

$$m_{z} = (x_{r-1,s} - x_{rs})(y_{rs} - y_{r+1,s}) - (x_{rs} - x_{r+1,s})(y_{r-1,s} - y_{rs})$$

$$\tilde{x} = \frac{1}{4R\sqrt{m_{\chi}^{2} + m_{y}^{2} + m_{z}^{2}}} \left\{ \int_{r-1,s}^{r} \left[ ln\left(\frac{\delta f}{a_{r-1,s}}\right) + \frac{1}{4} \right] + \int_{rs}^{r} \left[ ln\left(\frac{\delta g}{a_{rs}}\right) + \frac{1}{4} \right] \right\}$$

$$R = \frac{L_{r-1,s} L_{rs} \delta_{rs}}{\left[ 4L_{r-1,s}^{2} L_{rs} - \left(L_{r-1,s}^{2} + L_{rs}^{2} - \delta_{rs}^{2}\right)^{2} \right]^{1/2}}$$

L<sub>rs</sub> is as defined previously,

$$S_{rs} = \left[ \left( x_{r-1,s} - x_{r+1,s} \right)^2 + \left( y_{r-1,s} - y_{r+1,s} \right)^2 + \left( y_{r-1,s} - y_{r+1,s} \right)^2 \right]^{\frac{1}{2}}$$

$$f = \begin{cases} \frac{1}{L_{r-1,s}} \left[ 2R - \sqrt{4R^2 - L_{r-1,s}^2} \right], & L_{r-1,s}^2 \leq d_{rs}^2 + L_{rs}^2 \\ \frac{1}{L_{r-1,s}} \left[ 2R + \sqrt{4R^2 - L_{r-1,s}^2} \right], & L_{r-1,s}^2 > d_{rs}^2 + L_{rs}^2 \end{cases}$$

$$g = \begin{cases} \frac{1}{L_{rs}} \left[ 2R - \sqrt{4R^2 - L_{rs}^2} \right], & L_{rs}^2 \leq d_{rs}^2 + L_{r-1,s}^2 \\ \frac{1}{L_{rs}} \left[ 2R + \sqrt{4R^2 - L_{rs}^2} \right], & L_{rs}^2 > d_{rs}^2 + L_{r-1,s}^2 \end{cases}$$

If r = 1, self-induced effects must be modified to properly account for the proximity of the blade vortex. In this case,

$$\begin{aligned}
Q_{S_{\chi}}(x_{1s}, y_{1s}, y_{1s}) &= Q_{S_{\chi}}(x_{2s}, y_{2s}, y_{2s}, y_{2s}) \Big|_{\Gamma_{2s} \equiv 0} \\
Q_{S_{y}}(x_{1s}, y_{1s}, y_{1s}) &= Q_{S_{y}}(x_{2s}, y_{2s}, y_{2s}, y_{2s}) \Big|_{\Gamma_{2s} \equiv 0} \\
Q_{S_{y}}(x_{1s}, y_{1s}, y_{1s}) &= Q_{S_{y}}(x_{2s}, y_{2s}, y_{2s}) \Big|_{\Gamma_{2s} \equiv 0} \\
&- \frac{\Gamma_{S_{s}}}{\Delta \psi} \left\{ \frac{R}{b} \Delta \psi - \sqrt{\frac{R}{b} \Delta \psi} \left( \frac{R}{b} \Delta \psi + 2 \right) \right\} \\
&+ \ln \left[ 1 + \frac{R}{b} \Delta \psi + \sqrt{\frac{R}{b} \Delta \psi} \left( \frac{R}{b} \Delta \psi + 2 \right) \right] \right\}
\end{aligned}$$

where  $\Gamma_{B_s}$  is the strength of blade element s and  $\frac{R}{b}$  is the ratio of rotor radius to blade semichord. By the notation

$$q_{s_z}(x_{2s}, y_{2s}, z_{2s})|_{r_{2s}} \equiv 0$$

is meant the value for  $q_{s_z}(x_{2s},y_{2s},y_{2s})$  which is obtained if zero is substituted for the value of  $f_{2s}$ .

#### Effect of Fuselage

The following quantities, which are defined in The Formulations For The Supplementary Fuselage Program, are supplied as inputs from the supplemental fuselage program:

$$\sigma_{\overline{x}_{m}}, \sigma_{\overline{y}_{m}};$$

$$\xi_{k_{m}}, \eta_{k_{m}}, d_{k_{m}}; \overline{x}_{m}, \overline{y}_{m}, \overline{y}_{m};$$

$$\lambda_{\eta_{m}}, \mu_{\eta_{m}}, \nu_{\eta_{m}}; \lambda_{\xi_{m}}, \mu_{\xi_{m}}, \nu_{\xi_{m}};$$

$$m = 1, 2, \dots, N_{f} \quad \text{and} \quad k = 1, 2, 3, 4.$$

The fuselage contributions to the fluid velocity at a point (x,4.3) are given by

$$V_{\chi_{f}}(x,y,z) = \sum_{m=1}^{N_{f}} \left[ \sigma_{\chi_{m}} V_{\chi_{\infty}} + \sigma_{z_{m}} V_{z_{m}} \right] \left[ V_{\chi_{m}} + \overline{V}_{\chi_{m}} \right]$$

$$V_{y_{f}}(x,y,z) = \sum_{m=1}^{N_{f}} \left[ \sigma_{\chi_{m}} V_{\chi_{\infty}} + \sigma_{z_{m}} V_{z_{m}} \right] \left[ V_{y_{m}} - \overline{V}_{y_{m}} \right]$$

$$V_{z_{f}}(x,y,z) = \sum_{m=1}^{N_{f}} \left[ \sigma_{\chi_{m}} V_{\chi_{\infty}} + \sigma_{z_{m}} V_{z_{m}} \right] \left[ V_{z_{m}} + \overline{V}_{z_{m}} \right]$$

$$V_{z_{f}}(x,y,z) = \sum_{m=1}^{N_{f}} \left[ \sigma_{\chi_{m}} V_{\chi_{\infty}} + \sigma_{z_{m}} V_{z_{m}} \right] \left[ V_{z_{m}} + \overline{V}_{z_{m}} \right]$$

where

for

$$V_{x_{\infty}} = \frac{\mu}{\lambda} \cos \alpha_T$$

$$V_{3\infty} = -\left(\frac{\mu}{\lambda}\sin\alpha_7 + \sqrt{\frac{N_8}{2\lambda}}\right)K_f$$

and  $K_f$  is a correction factor, supplied as an input parameter, whose evaluation is discussed in Procedure For Implementation Of The Programs.

The quantities  $V_{x_m}, V_{y_m}$  and  $V_{x_m}$  are computed in the following manner. Using matrix notation,

$$\begin{bmatrix} V_{\chi_m} \\ V_{y_m} \\ V_{y_m} \end{bmatrix} = \begin{bmatrix} \lambda_{\xi_m} \lambda_{\eta_m} \lambda_{\xi_m} \\ \mu_{\xi_m} \mu_{\eta_m} \mu_{\xi_m} \\ \nu_{\eta_m} \\ \nu_{\xi_m} \end{bmatrix} \begin{bmatrix} V_{\xi_m} \\ V_{\eta_m} \\ V_{\xi_m} \end{bmatrix}$$

$$\begin{bmatrix} V_{\xi_m} \\ V_{\eta_m} \\ V_{\xi_m} \end{bmatrix}$$

$$(14)$$

where  $\lambda_{\xi_m}, \mu_{\xi_m}$  and  $\nu_{\xi_m}$  are given in terms of input quantities:

$$\lambda_{\xi_m} = \mu_{\eta_m} \nu_{\xi_m} - \mu_{\xi_m} \nu_{\eta_m}$$

$$\mu_{\xi_m} = \nu_{\eta_m} \lambda_{\xi_m} - \nu_{\xi_m} \lambda_{\eta_m}$$

$$\nu_{\xi_m} = \lambda_{\eta_m} \mu_{\xi_m} - \lambda_{\xi_m} \mu_{\eta_m}$$

The quantities  $V_{\xi_m}$ ,  $V_{\eta_m}$  and  $V_{\xi_m}$  are obtained in the following manner. First,  $d_{\xi_m}^2$  and  $d_{\xi_m}^2$  are computed:

$$d_{5m}^{2} = (\xi_{3m} - \xi_{1m})^{2} + (\eta_{3m} - \eta_{1m})^{2}$$

$$d_{6m}^{2} = (\xi_{+m} - \xi_{2m})^{2} + (\eta_{+m} - \eta_{2m})^{2}$$

and  $d_{7m}^2$  is set equal to the larger of  $d_{5m}^2$  or  $d_{6m}^2$ . Then  $\xi_m, \eta_m$  and  $\zeta_m^*$  are obtained from

$$\begin{bmatrix} \xi_{m} \\ \eta_{m} \\ \zeta_{m} \end{bmatrix} = \begin{bmatrix} \lambda_{\xi_{m}} \mu_{\xi_{m}} \nu_{\xi_{m}} \\ \lambda_{\eta_{m}} \mu_{\eta_{m}} \nu_{\eta_{m}} \\ \lambda_{\xi_{m}} \mu_{\xi_{m}} \mu_{\xi_{m}} \end{bmatrix} \begin{bmatrix} x - \overline{x}_{m} \\ y - \overline{y}_{m} \\ 3 - \overline{y}_{m} \end{bmatrix}$$

$$(15)$$

.  $1 r_{o_m}^2$  is computed from

$$r_{o_m}^2 = \xi_m^2 + \eta_m^2 + \zeta_m^2$$

Also,  $t_m^2$  is obtained according to

$$t_m^2 = \frac{r_{o_m}^2}{d_{7m}^2} \tag{16}$$

If  $t_m^2 > 6$ , an approximate method is used to compute  $V_{\xi_m}$ ,  $V_{\eta_m}$  and  $V_{\zeta_m}$ . If  $t_m^2 \le 6$  the exact method is used (the accuracy of the approximate method is discussed in Reference 8).

# Approximate Method $(t_m^2 > 6)$

$$V_{\xi_m} = \frac{S_m \, \xi_m}{r_{o_m}^3}$$

$$V_{\eta_m} = \frac{S_m \eta_m}{r_{o_m}^3}$$

$$V_{S_m} = \frac{S_m S_m}{r_{o_m}^3}$$
(17)

where

$$S_m = \frac{1}{2} (\xi_{3m} - \xi_{1m}) (\eta_{2m} - \eta_{4m})$$

## Exact Method $(t_m^2 \le 6)$

The following additional quantities are computed if the exact method is used (note: if a vertex subscript k = 5 is called for in any of the following equations this is understood to mean that k = 1 is to be used):

$$r_{km} = \left\{ \left( \xi_{m} - \xi_{km} \right)^{2} + \left( \eta_{m} - \eta_{km} \right)^{2} + \xi_{m}^{2} \right\}^{1/2}$$

$$e_{km} = \xi_{m}^{2} + \left( \xi_{m} - \xi_{km} \right)^{2}$$

$$h_{km} = \left( \eta_{m} - \eta_{km} \right) \left( \xi_{m} - \xi_{km} \right)$$

$$m_{km} = \frac{\eta_{k+1,m} - \eta_{km}}{\xi_{k+1,m} - \xi_{km}}$$
all for  $k = 1, 2, 3, 4$ . Then

where the arctangent is understood to lie between  $-\frac{\pi}{2}$  and  $\frac{\pi}{2}$ .

The computation of  $\overline{V}_{x_m}$ ,  $\overline{V}_{y_m}$  and  $\overline{V}_{3_m}$  is identical to that of  $V_{x_m}$ ,  $V_{y_m}$  and  $V_{5_m}$ , respectively, except that instead of evaluating the various functions at the point (x, y, y), the point (x, y, y) is used. That is,

$$\overline{V}_{x_{m}}(x, y, 3) = V_{x_{m}}(x, -y, 3)$$

$$\overline{V}_{y_{m}}(x, y, 3) = V_{y_{m}}(x, -y, 3)$$

$$\overline{V}_{3_{m}}(x, y, 3) = V_{3_{m}}(x, -y, 3)$$
(19)

## 4. FORMULATIONS FOR THE SUPPLEMENTARY FUSELAGE PROGRAM

#### PRELIMINARY REMARKS

The formulations given below generally correspond to those reported in Reference 8, but adapted to the problem treated here. Referring now to the coordinate system of the section on Coordinate Identifications And Nomenclature above, it is assumed that the fuselage is symmetric with respect to the x-z plane and that the free stream is parallel to that plane.

As a first step, that half of the fuselage for which y is positive is approximated by a mesh of quadrilateral elements. Those portions of the surface having large curvature must, of course, be divided into smaller elements than are adequate elsewhere. The elements are numbered sequentially, beginning with some convenient element, say at the nose.

Consider the  $m^{th}$  quadrilateral element  $(m = 1, 2, \dots, N_f)$ ; its four vertices are numbered clockwise when viewing the element from the exterior of the fuselage, the selection of vertex 1 being arbitrary. The coordinates of these vertices, denoted  $(x_{k_m}, y_{k_m}, y_{k_m},$ 

#### EQUATIONS FOR COMPUTATION

The major portion of the program is directed to obtaining two sets of linear algebraic equations having the normalized source strengths as unknowns.

These two sets of equations may be written in the form

$$\sum_{n=1}^{N_f} B_{mn} O_{z_n} = -\lambda_{\xi_m},$$

$$\sum_{n=1}^{N_f} B_{mn} O_{z_n} = -\lambda_{\xi_m},$$
(20)

The program then solves these equations by a standard iterative technique (convergence is rapid because the matrix of the coefficients  $B_{mn}$  is very nearly diagonal) to obtain the  $\sigma_{x_m}$ 's and  $\sigma_{x_m}$ 's.

The coefficients and inhomogeneous terms of Equations (20) are computed as follows. First, let

$$B_{mn} = A_{mn} + \overline{A}_{mn} \tag{21}$$

 $A_{mn}$  and  $\overline{A}_{mn}$  relate directly to the velocities induced by element n and its image, respectively, on element m.

### Computation of Amn

First, the quantities

$$\alpha_{N_{n}} = (y_{4n} - y_{2n})(y_{3n} - y_{1n}) - (y_{4n} - y_{2n})(y_{3n} - y_{1n})$$

$$\beta_{N_{n}} = (y_{4n} - y_{2n})(x_{3n} - x_{1n}) - (x_{4n} - x_{2n})(y_{3n} - y_{1n})$$

$$\gamma_{N_{n}} = (x_{4n} - x_{2n})(y_{3n} - y_{1n}) - (y_{4n} - y_{2n})(x_{3n} - x_{1n})$$

$$\overline{\gamma}_{N_{n}} = \frac{1}{4} \sum_{k=1}^{4} x_{kn}, \quad \overline{y}_{n} = \frac{1}{4} \sum_{k=1}^{4} y_{kn}, \quad \overline{y}_{kn} = \frac{1}{4} \sum_{k=1}^{4} y_{kn};$$
(22)

are computed. These quantities are then used to compute

$$\chi_{kn}^{"} = \frac{1}{(\alpha_{N_{n}}^{2} + \beta_{N_{n}}^{2} + \gamma_{N_{n}}^{2})} \left\{ (\beta_{N_{n}}^{2} + \gamma_{N_{n}}^{2}) (x_{kn} - \bar{x}_{n}) - \alpha_{N_{n}} \beta_{N_{n}} (y_{kn} - \bar{y}_{n}) - \alpha_{N_{n}} \gamma_{N_{n}} (y_{kn} - \bar{y}_{n}) \right\}$$

$$y_{kn}^{"} = \frac{1}{(\alpha_{N_{n}}^{2} + \beta_{N_{n}}^{2} + \gamma_{N_{n}}^{2})} \left\{ (\alpha_{N_{n}}^{2} + \gamma_{N_{n}}^{2}) (y_{kn} - \bar{y}_{n}) - \beta_{N_{n}} \alpha_{N_{n}} (x_{kn} - \bar{x}_{n}) - \beta_{N_{n}} \gamma_{N_{n}} (y_{kn} - \bar{y}_{n}) \right\}$$

$$y_{kn}^{"} = \frac{1}{(\alpha_{N_{n}}^{2} + \beta_{N_{n}}^{2} + \gamma_{N_{n}}^{2})} \left\{ (\alpha_{N_{n}}^{2} + \beta_{N_{n}}^{2}) (y_{kn} - \bar{y}_{n}) - \gamma_{N_{n}} \alpha_{N_{n}} (x_{kn} - \bar{x}_{n}) - \gamma_{N_{n}} \beta_{N_{n}} (y_{kn} - \bar{y}_{n}) \right\}$$

$$y_{kn}^{"} = \frac{1}{(\alpha_{N_{n}}^{2} + \beta_{N_{n}}^{2} + \gamma_{N_{n}}^{2})} \left\{ (\alpha_{N_{n}}^{2} + \beta_{N_{n}}^{2}) (y_{kn} - \bar{y}_{n}) - \gamma_{N_{n}} \alpha_{N_{n}} (x_{kn} - \bar{x}_{n}) - \gamma_{N_{n}} \beta_{N_{n}} (y_{kn} - \bar{y}_{n}) \right\}$$

for k = 1, 2, 3, and 4. These transformed coordinates are then utilized to compute the direction cosines  $\lambda_{\xi_n}, \mu_{\xi_n}, \nu_{\xi_n}$ :

$$\begin{bmatrix}
\lambda_{\xi_{n}} \\
\mu_{\xi_{n}}
\end{bmatrix} = \left[ \left( \chi_{3n}^{"} - \chi_{1n}^{"} \right)^{2} + \left( y_{3n}^{"} - y_{1n}^{"} \right)^{2} + \left( y_{3n}^{"} - y_{1n}^{"} \right)^{2} \right]^{-1/2} \begin{bmatrix} \chi_{3n}^{"} - \chi_{1n}^{"} \\
y_{3n}^{"} - y_{1n}^{"} \\
y_{3n}^{"} - y_{1n}^{"}
\end{bmatrix} \tag{24}$$

Then 
$$\lambda_{\zeta_n}, \mu_{\zeta_n}$$
 and  $\nu_{\zeta_n}$  are computed according to
$$\begin{bmatrix} \lambda_{\zeta_n} \\ \mu_{\zeta_n} \\ \nu_{\zeta_n} \end{bmatrix} = \begin{bmatrix} \alpha_{N_n}^2 + \beta_{N_n}^2 + \gamma_{N_n}^2 \end{bmatrix}^{-1/2} \begin{bmatrix} \alpha_{N_n} \\ \beta_{N_n} \\ \gamma_{N_n} \end{bmatrix}$$
(25)

and the direction cosines obtained from Equations (24) and (25) are used in the computation of  $\lambda_{\eta_n}$ ,  $\mu_{\eta_n}$  and  $\nu_{\eta_n}$ :

$$\lambda_{\eta_n} = \mu_{\xi_n} \nu_{\xi_n} - \mu_{\xi_n} \nu_{\xi_n}$$

$$\mu_{\eta_n} = \nu_{\xi_n} \lambda_{\xi_n} - \nu_{\xi_n} \lambda_{\xi_n}$$

$$\nu_{\eta_n} = \lambda_{\xi_n} \mu_{\xi_n} - \lambda_{\xi_n} \mu_{\xi_n}$$
(26)

Then, the following transformed coordinates are computed:

$$\begin{bmatrix}
\xi_{mn} \\
\eta_{mn}
\end{bmatrix} = \begin{bmatrix}
\lambda_{\xi_{n}} \mu_{\xi_{n}} \nu_{\xi_{n}} \\
\lambda_{\eta_{n}} \mu_{\eta_{n}} \nu_{\eta_{n}}
\end{bmatrix} \begin{bmatrix}
\bar{\varkappa}_{m} - \bar{\varkappa}_{n} \\
\bar{y}_{m} - \bar{y}_{n}
\end{bmatrix} \begin{bmatrix}
\bar{\varkappa}_{m} - \bar{\varkappa}_{n} \\
\bar{\varkappa}_{m} - \bar{\varkappa}_{n}
\end{bmatrix} (27a)$$

$$\begin{bmatrix} \xi_{kn} \\ \eta_{kn} \end{bmatrix} = \begin{bmatrix} \lambda_{\xi_n} \mu_{\xi_n} \nu_{\xi_n} \\ \lambda_{\eta_n} \mu_{\eta_n} \nu_{\eta_n} \end{bmatrix} \begin{bmatrix} \chi_{k''} \\ y_{k''} \\ \chi_{k''} \end{bmatrix}$$
(27b)

Next, the quantities

$$d_{5n}^{2} = (\xi_{3n} - \xi_{1n})^{2} + (\eta_{3n} - \eta_{1n})^{2}$$

$$d_{6n}^{2} = (\xi_{4n} - \xi_{2n})^{2} + (\eta_{4n} - \eta_{2n})^{2}$$
(28)

are obtained, and  $d_{7n}^2$  is defined to be the larger of  $d_{5n}^2$  or  $d_{6n}^2$ . Then

$$r_{o_{mn}}^{z} = \xi_{mn}^{z} + \eta_{mn}^{z} + \zeta_{mn}^{z} \tag{29}$$

and the quantity

$$t_{mn}^{2} = \frac{r_{o_{mn}}^{2}}{d_{7n}^{2}} \tag{30}$$

are computed. If  $t_{mn}^2 > 6$ , an approximate method is used. If  $t_{mn}^2 \le 6$ , the exact formulation is applied. In either case, the quantities  $V_{\xi_{mn}}, V_{\eta_{mn}}$  and  $V_{\zeta_{mn}}$  are computed, which in turn are used to evaluate

$$\begin{bmatrix} V_{z_{mn}} \\ V_{y_{mn}} \\ V_{y_{mn}} \end{bmatrix} = \begin{bmatrix} \lambda_{\xi_n} \lambda_{\eta_n} \lambda_{\xi_n} \\ \mu_{\xi_n} \mu_{\eta_n} \mu_{\xi_n} \\ \nu_{\xi_n} \nu_{\eta_n} \nu_{\xi_n} \end{bmatrix} \begin{bmatrix} V_{\xi_{mn}} \\ V_{\eta_{mn}} \\ V_{\xi_{mn}} \end{bmatrix}$$
(31)

whereupon

$$A_{mn} = \lambda_{\zeta_m} V_{x_{mn}} + \mu_{\zeta_m} V_{y_{mn}} + \nu_{\zeta_m} V_{z_{mn}}$$
 (32)

## Computation of $V_{\xi_{mn}}, V_{\eta_{mn}}, V_{\xi_{mn}}$ by Approximate Method $(t_{mn}^2 > 6)$

In this case,

$$\begin{bmatrix} V_{\bar{s}_{mn}} \\ V_{\eta_{mn}} \\ V_{\bar{s}_{mn}} \end{bmatrix} = \frac{S_n}{\dot{r}_{o_{mn}}^3} \begin{bmatrix} \dot{s}_{mn} \\ \eta_{mn} \\ \dot{s}_{mn} \end{bmatrix}$$
(33)

where

$$S_n = \frac{1}{2} \left[ \xi_{3n} - \xi_{1n} \right] \left[ \eta_{2n} - \eta_{4n} \right]$$

## Computation of $V_{\xi_{mn}}$ , $V_{\eta_{mn}}$ , $V_{\zeta_{mn}}$ by Exact Method $(t_{mn}^2 \le 6)$

The following additional quantities are first computed (note: in the following equations, if a vertex subscript k = 5 is called for, this is understood to mean that k = 1 is to be used):

$$d_{kn} = \left[ \left( \xi_{k+1,n} - \xi_{kn} \right)^{2} + \left( \eta_{k+1,n} - \eta_{kn} \right)^{2} \right]^{1/2}$$

$$r_{kmn} = \left[ \left( \xi_{mn} - \xi_{kn} \right)^{2} + \left( \eta_{mn} - \eta_{kn} \right)^{2} + \xi_{mn}^{2} \right]^{1/2}$$

$$e_{kmn} = \xi_{mn}^{2} + \left( \xi_{mn} - \xi_{kn} \right)^{2}$$

$$h_{kmn} = \left( \eta_{mn} - \eta_{kn} \right) \left( \xi_{mn}^{2} - \xi_{kn} \right)$$

$$m_{kn} = \frac{\eta_{k+1,n} - \eta_{kn}}{\xi_{k+1,n} - \xi_{kn}}$$

all for k = 1, 2, 3, and 4.

Then

$$V_{\xi_{mn}} = \sum_{k=1}^{4} \frac{(\eta_{k+1,n} - \eta_{kn})}{d_{kn}} ln \left[ \frac{r_{kmn} + r_{k+1,mn} - d_{kn}}{r_{kmn} + r_{k+1,mn} + d_{kn}} \right]$$

$$V_{\eta_{mn}} = \sum_{k=1}^{4} \frac{(\xi_{kn} - \xi_{k+1,n})}{d_{kn}} ln \left[ \frac{r_{kmn} + r_{k+1,mn} - d_{kn}}{r_{kmn} + r_{k+1,mn} + d_{kn}} \right]$$

$$V_{\xi_{mn}} = \sum_{k=1}^{4} \left\{ tan^{-1} \left[ \frac{m_{kn} e_{kmn} - h_{kmn}}{\xi_{mn} r_{kmn}} \right] - tan^{-1} \left[ \frac{m_{kn} e_{k+1,mn} - h_{k+1,mn}}{\xi_{mn} r_{k+1,mn}} \right] \right\}$$

where the arctangent is defined for the interval  $-\frac{\pi}{2}$  to  $\frac{\pi}{2}$ .

## Computation of $\overline{A_{mn}}$

The computation of  $\overline{A}_{mn}$  is carried out in the same manner as that of  $A_{mn}$ , with two exceptions. First, the  $\overline{y}$  coordinate of element m is replaced by its negative; specifically,  $(\overline{x}_m, \overline{y}_m, \overline{y}_m)$  are replaced by  $(\overline{x}_m, \overline{y}_m, \overline{y}_m)$  in the computation of  $\xi_{mn}$ ,  $\eta_{mn}$  and  $\xi_{mn}$ . Second, the formula for  $A_{mn}$  is altered slightly so that

$$\bar{A}_{mn} = \lambda_{\xi_m} \bar{V}_{x_{mn}} - \mu_{\xi_m} \bar{V}_{y_{mn}} + \nu_{\xi_m} \bar{V}_{y_{mn}}$$
 (35)

where the bars over  $V_{z_{mn}}$  etc., indicate that they were obtained using  $\bar{y}_m$  in place of  $\bar{y}_m$ .

It should be noted that certain indeterminacies are encountered in the formulas for  $A_{mn}$  (but not  $\overline{A}_{mn}$ ) when m=n. The computation of  $A_{mn}$  is, therefore, omitted, and the proper limiting value for that quantity of  $2\pi$  is specified.

#### 5. PROCEDURES FOR IMPLEMENTATION OF THE PROGRAMS

#### THE MAIN PROGRAM

#### Assignment of Input Parameters

There are a number of input parameters, certain of which relate directly to aircraft flight conditions, and others which must be chosen on the basis of past experience and best judgement. Each of the input parameters is discussed individually below. A sample collection of these parameters is then given for a representative aircraft and flight condition.

#### 1. Advance Ratio $\mu$

Given the aircraft forward speed  $V_{\mathcal{F}}$  in feet per second, rotor radius R in feet and rotor angular speed  $\Omega$  in radians per second,  $\mu$  is calculated according to

$$\mu = \frac{V_f}{OR} \tag{36}$$

#### 2. Number of Blades $N_R$

The program has the facility to handle rotors with up to four blades.

#### 3. Loading Parameter $\lambda$

This parameter is given by

$$\lambda = \frac{4W}{\pi^2 N_B \rho \Omega^2 R^4} \tag{37}$$

where  $n_{,R}$  and  $N_{B}$  are as defined in 1 and 2,  $\rho$  is the air density in slugs per cubic foot, and W is the total weight of the aircraft, in pounds.

#### 4. Tip-Path-Plane Angle $\alpha_7$ , in Degrees

In the absence of measured data, the value for this angle may be estimated by the formula

$$\alpha_{\tau} = \left(\frac{360}{\pi^2 N_B}\right) \frac{C_{D_F} \mu^2}{\lambda} , \text{ degrees}$$
 (38)

where  $C_{D_{\!f}}$  is the drag coefficient of the fuselage, defined by

$$C_{D_f} = \frac{D_f}{\sqrt{2\rho V_f^2 \pi R^2}}$$
 where  $D_f$  is fuselage drag.

5. Number of Azimuth Stations per Revolution, NA.

Since running time increases rapidly with increasing  $N_A$  (approximately as  $N_A^3$ ), a careful choice for this number must be made. It has been found that for a two-bladed rotor sufficient accuracy may be obtained with  $N_A = 12$ . It is difficult to define time variations of fluid velocities if  $N_A$  is less than this number (for  $N_{\sigma} = 2$ ), and running time becomes excessive if it is made larger.

6. Number of Revolutions of Wake per Blade, N<sub>R</sub>.

The total number of wake elements included is proportional to  $N_R$ , so running time is also sensitive to this number. Generally, the higher the advance ratio, the smaller the value of  $N_R$  needed, provided interest in the flow is not directed to the far wake. For example,  $N_R = 2$  is sufficient for  $\mu = .25$  and  $N_R = 4$  suffices for  $\mu = .15$ , to satisfactorily reproduce the flow directly beneath the rotor plane.

7. The Strength of Blade Element 1 as a Function of Azimuth

The normalized strength of blade element 1 at each azimuth station must be specified. In the absence of measured data, the formula

$$\Gamma_{E_{i}}(\psi) = 1 - 2\mu \sin \psi \tag{39}$$

provides a suitable appr ximation.

8. The Core Size of Each Wake Element,  $a_{ij}$ , at the Start of the Program

Each wake element (i,j) for  $i=1, 2, \ldots, N_R N_A$  and  $j=1, 2, \ldots, N_B$  must be assigned a core size in order to start the program. It has been found, by estimating the core sizes of wake vortices for numerous flight conditions, that

$$a_{ij}(\psi_{init}) = .05 \qquad \qquad i = 1, 2, \cdots, N_R N_A j = 1, 2, \cdots, N_B$$
 (40)

can be utilized for any normal operating condition of the rotor. The variations in core size from this value with changes in advance ratio and loading were found to be negligible in their effect on the flow.

9. The Core Size of the Wake Element Attached to Blade 1,  $a_{tt}$ , as a Function of Azimuth

For the same reasons as noted in item (8) above, it is sufficient to let

$$a_{11}(\psi) = .05$$
 (41)

10. The Initial Value for the Azimuth Position of Blade 1,  $\psi_{init}$ , in Degrees, and the Number of Rotor Revolutions to be run,  $N_{RV}$ .

The value for  $\psi_{init}$  is, of course, arbitrary, and is generally made zero. If a case is being investigated for which a periodic flow may be obtained (which generally occurs for  $\mu$  greater than about .08), it is desirable to make  $N_{RV}$  large enough to allow periodicity to be established. It has been found that, for a two-bladed rotor, a periodic flow is usually obtained after about  $N_R$  revolutions of the rotor. That is, if

$$N_{RY} \ge N_R$$
 (42)

a periodic flow will be established.

# 11. Initial Wake Configuration

The option has been provided whereby the initial wake geometry; i.e., the coordinates of the wake reference points  $P_{ij}$ ,  $i=1,2,\cdots,N_AN_R+1$ ,  $j=1,2,\cdots,N_B$ ; may be specified as inputs or may be computed as part of the program. The computed configuration is a skewed helix with skew and pitch dependent on  $\mu$  and  $\lambda$ . The option for specifying the geometry as input allows the program to be continued from a previously computed geometry. Thus, if additional information is desired after a run has been completed, the program may be restarted at the point where periodicity has been established rather than from a skew-helical configuration.

### 12. Coordinates of Points at Which Flow is to be Determined

The xy and 3 coordinates of those points at which fluid velocity components are desired should be specified. The maximum number of points which can be handled is 300.

# 13. Correction Factor $K_{\mathcal{F}}$

The value for the 3-component of the free stream experienced by the fuselage, which is needed to assign the strengths of the fuselage source elements, may be estimated, using momentum considerations, to be

$$-\left(\frac{\mu}{\lambda}\sin\alpha_T+\sqrt{\frac{N_{\delta}}{2\lambda}}\right).$$

It has been found, though, that the average downwash experienced by the fuselage may, in some cases, differ considerably from this value. Therefore, a correction factor  $K_f$  has been applied to make the downwash used correspond to the correct value. The following procedure may be used to obtain the value of  $K_f$ .

First, the main program is run, with the fuselage representation omitted, until a periodic flow is established. The fluid velocity is computed during this run at several points (it has been found that 25 points are sufficient for a UH-1B fuselage) within the volume which the fuselage occupies. A simple average over one period of the value of  $V_3$ , as given on the output sheet,

is then computed for each point, and the spacial average of these is in turn computed. Denote this combined spacial and time average of  $V_3$  by  $\overline{V}_3$ . Then  $K_f$  is simply given by

$$K_{f} = \frac{-\overline{V}_{3}}{\left(\frac{\mu}{\lambda} \sin \alpha_{T} + \sqrt{\frac{N_{B}}{2\lambda}}\right)} \tag{43}$$

# 14. Fuselage Parameters

All the parameters necessary for inclusion in the main program to represent the fuselage are obtained directly from the supplemental fuselage program. The latter program has been coded to punch the cards needed directly.

# SAMPLE PROBLEM

For illustrative purposes, consider a UH-1B helicopter operating at a forward speed of 60 knots and a rotor speed of 300 rpm. The total weight of the aircraft is 5675 pounds, the drag coefficient of the fuselage,  $C_{D_{\it f}}$ , is .014, the rotor radius is 22 feet and the blade semichord is 10.5 inches. A programmer would then need, in addition to the appropriate outputs from the supplemental fuselage program, the information listed below.

Number of blades  $N_{\mathcal{S}} = 2$ 

Number of Revolutions of Wake  $N_R = 4$ 

Number of Azimuth Stations Na = 12

 $\lambda = .00209$ 

 $\mu = .1465$ 

 $\alpha_r = 2.62 \text{ degrees}$ 

 $V_{3\infty}$  correction factor  $K_f = .2600$ 

$$\frac{R}{h} = 25.1$$

Number of fuselage elements  $N_f = 96$ 

 $\Psi$  initial = 0

 $N_{RV} = 4.5$ 

AZIMUTR		
Ψ − deg	$f_{B_1}(\psi)$	Q11 (4)
0	1.0	.05
30	.8535	
60	.746	
90	.707	
120	.746	
150	,8535	
180	1.0	
210	1.1465	
240	1.254	
270	1.293	
300	1.254	
330	1.1465	*

Velocities are to be computed at:

x	У	3
-1	. 3	4
5	. 3	4
0	. 3	4
. 5	. 3	4
1.0	. 3	4

Selected pages from the output for this case are shown on the following pages. The first of these, listing the parameters, is self-explanatory. On the next pages, the station number, running from 1 to 49, refers to the first (i) subscript of the wake reference points, and, of course, the blade number is the second subscript (i). All velocity components printed out, i.e., those at the wake reference points and those at other points, are the quantities defined by Equations (3). Thus, the actual velocity components at the points in question, in dimensional form, would be obtained by multiplying the print-out variable by  $(\lambda)$   $(\Omega R)$ .

### THE SUPPLEMENTAL FUSELAGE PROGRAM

Operation of the supplemental fuselage program requires specification of the number  $N_f$  of fuselage elements to be considered and the coordinates of the four vertices of each of these elements. As noted previously, the size of these elements must be varied, depending on local curvature and the accuracy of the flow representation desired. Computing time for the main program increases rapidly with  $N_f$ , so as large an element size as possible, compatible with accuracy requirements, should be selected.

As an example, the inputs used for computing the source strengths needed to represent an idealized UH-1B fuselage are tabulated on the pages which follow. The element sizes chosen for this case appear to provide a reasonable compromise in meeting running time and accuracy requirements. Note that the vertices are numbered in the clockwise sense with the element viewed from outside the fuselage.

# HELICOPTER WAKE VORTICITY PROGRAM

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2528E 01 0.86603E 00 -0.93308E 00 0.74242E 02 0.33311E 01 -0.94749E 01 0.92458E 00 0.500000000000000000000000000000000	13094E 0	0.300005.0	0.878195	729516 0	. 3129UE	376	30441.	500005
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35480E 01 0.5000CE 00 -0.96052E CO 0.70169E 02 -0.12675E 01 -0.94749E 01 0.92675E 00 0.50000 0.50000 0.50000 0.70045E 02 -0.19994E 00 -0.96375E 01 0.10732E 01 0.50000 0.50000 0.70045E 02 0.70574E 00 -0.10520E 02 0.12702E 01 0.50000 0.71838E 02 0.76774E 00 -0.10520E 02 0.12702E 01 0.50000 0.71838E 02 0.77546E 01 -0.10566E 02 0.12735E 01 0.50000 0.71838E 02 0.77546E 01 -0.10566E 02 0.12735E 01 0.50000 0.77676E 01 0.774195E 02 0.77746E 01 -0.10566E 02 0.12735E 01 0.50000 0.77885E 01 0.774195E 02 0.77746E 01 -0.10566E 02 0.12735E 01 0.50000 0.7767E 01 0.72658E 02 -0.37960E 01 -0.15282E 02 0.12735E 01 0.50000 0.72658E 02 0.12735E 01 0.50000 0.72658E 02 0.12735E 01 0.50000 0.72659E 01 0.72659E 02 0.12735E 01 0.50000 0.72659E 01 0.72659E 01 0.72659E 02 0.79975E 00 0.50000 0.72659E 01 0.7775E 01 0.72659E 01 0.7775E 01 0.72659E 01 0.7775E 01 0.72659E 01 0.7775E 01 0.7775E 01 0.7775E 01 0.7775E 01 0.7775E 01 0.77775E 01 0.777775E 01 0.7777775E 01 0.7777775E 01 0.7777775E 01 0.7777775E 01 0.7777775E 01 0.7777775E 01 0.777777775E 01 0.7777777777777777777777777777777777	31053E 0	0.86603E 0	0.93308E 0	.71579E 0	0.47007E	42E	.79975E	- 50000E-
37586f 01 0.42911E-06 -0.38797E 00 0.70045E 02 -0.19994E 00 -0.96375E 01 0.10732E 01 0.50000 37586f 01 -0.50000E 00 -0.10154E 01 0.70261E 02 0.76774E 00 -0.10520E 02 0.12735E 01 0.50000 34118E 01 -0.86603E 00 -0.10429E 01 0.71838E 02 0.37960E 01 -0.10566E 02 0.12735E 01 0.50000 22551E 01 -0.86603E 00 -0.10738E 01 0.77495E 02 -0.99448E 00 -0.11655E 02 0.12735E 01 0.50000 22551E 01 -0.86603E 00 -0.10778E 01 0.72658E 02 -0.99746E 00 -0.11655E 02 0.12735E 01 0.50000 22183E 01 -0.86603E 00 -0.11526E 01 0.72658E 02 -0.91466E 01 -0.11655E 02 0.10732E 01 0.50000 22183E 01 -0.34168E-06 -0.11852E 01 0.72658E 02 0.25802E 00 -0.11538E 02 0.10732E 01 0.50000 22183E 01 0.50000 0 -0.11801E 01 0.72658E 02 0.79975E 00 0.50000 24289E 01 0.50000 0 -0.12675E 01 0.72659E 01 0.72659E 01 0.72650E 00 0.50000 24289E 01 0.50000 0 -0.11801E 01 0.72659E 01 0.72650E 01 0.72650E 01 0.72650E 01 0.50000 0 -0.12624E 01 0.72650E 01 0.734168 01 0.50000 01 0.72650E 01 0.734168 01 0.73416	35480E 0	0.5000CE 0	0.96052E C	.70169E 0	0.12675E	49E	.92675E	- 50000E-
37012L 01 -0.50000E 00 -0.10154E 01	37586F 0	0.429116-0	0.387978 0	.70045E 0	0.19994E	175E	.10732E	-50000E-
34118E 01 -0.86603E 00 -0.10429E 01 0.71838E 02 0.37960E 01 -0.10566E 02 0.12735E 01 0.50000 2.3885E C1 -0.1000CE 01 -0.10703E C1 0.74195E 02 -0.9548E 00 -0.41586E 01 0.12735E 01 0.50000 2.5651E 01 -0.1000CE 01 -0.1077E 01 0.774195E 02 -0.37689E 01 -0.11655E 02 0.12702E 01 0.50000 2.2757E 01 -0.50600E 00 -0.11252E 01 0.72658E 02 -0.31666E 01 -0.15282E 02 0.12702E 01 0.50000 2.2183E 01 -0.56000E 00 -0.11526E 01 0.72658E 02 -0.31666E 01 -0.15695E 02 0.92675E 00 0.50000 2.2183E 01 0.50000E 00 -0.11801E 01 0.72658E 02 0.33524E 01 -0.13854E 02 0.79975E 00 0.50000 2.2183E 01 0.50000E 01 -0.12350E 01 0.72658E 02 0.71475E 01 0.98603E 01 0.72650E 00 0.500	37012L 0	-0.50000E 0	0-10154E 0	.70261E 0	.76774E	20E	.12002E	- 50000E-
2385L C1 -0.1003CE 01 -0.10703E C1 0.74195E 02 -0.95348E 00 -0.41586E 01 0.12735E 01 0.5000 25651E 01 -0.86603E 00 -0.10977E 01 0.73790E 02 -0.37689E 01 -0.11655E 02 0.12002E 01 0.50000 22187E 01 -0.56000E 00 -0.11526E 01 0.72658E 02 -0.31666E 01 -0.15282E 02 0.07975E 01 0.50000 24289E 01 0.56000E 00 -0.11801E 01 0.72161E 02 0.23524E 01 -0.15285E 02 0.79975E 00 0.50000 28716E 01 0.56000E 00 -0.12075E 01 0.72658E 02 0.71450E 01 -0.98800E 01 0.72650E 00 0.50000 3482E 01 0.86603E 00 -0.12624E 01 0.72653E 02 0.41173E 01 -0.23950E 01 0.72650E 00 0.50000 4675E 01 0.50000E 00 -0.12624E 01 0.71477E 02 0.86513E 00 -0.23739E 01 0.79975E 00 0.50000	34118E 0	-0.86603E 0	0.10429E 0	.71838E 0	.37960E	999	.12735E	. 50000E-
25551E 01 -0.886035E 0U -0.110977E 01 0.73790E 02 -0.37689E 01 -0.11655E 02 0.12002E 01 0.50000 22157E 01 -0.36600E 00 -0.1152E 01 0.72658E 02 -0.31466E 01 -0.15659E 02 0.10732E 01 0.50000 22183E 01 -0.34680E 00 -0.1152E 01 0.72658E 02 0.23802E 00 -0.15659E 02 0.79975E 00 0.50000 24289E 01 0.56000E 00 -0.11801E 01 0.72658E 02 0.33524E 01 -0.13854E 02 0.79975E 00 0.50000 24782E 01 0.86603E 00 -0.12075E 01 0.72653E 02 0.71456E 01 -0.98800E 01 0.72650E 00 0.50000 34782E 01 0.08603E 00 -0.12350E 01 0.72653E 02 0.41173E 01 -0.23950E 01 0.772650E 00 0.50000 44782E 01 0.50000E 01 -0.12350E 01 0.71477E 02 0.88513E 01 -0.23950E 01 0.79975E 00 0.50000	238855	-0.1000ce o	0.10703E C	.74195E 0	0.95348E	86E	12735E	. 50000E
22183E 01 -0.34168E-06 -0.11526E 01 0.72161E 02 0.25802E 00 -0.13659E 02 0.92675E 00 0.50000 24289E 01 0.50000E 00 -0.11801E 01 0.72161E 02 0.25802E 00 -0.13854E 02 0.79975E 00 0.50000 24782E 01 0.86603E 00 -0.12075E 01 0.72653E 02 0.71450E 01 -0.98800E 01 0.72650E 00 0.50000 34782E 01 0.86603E 00 -0.12350E 01 0.72533E 02 0.41173E 01 -0.23950E 01 0.72650E 00 0.50000 4675E 01 0.50000E 00 -0.12850E 01 0.71477E 02 0.88513E 00 -0.2739E 01 0.79975E 00 0.50000	23631E U	0.50003E	0.109775 0	72450E 0	. 70689E	10 C	120025	- 20000E-
24289£ 01 0.50000E 00 -0.11801E 01 0.72054E 02 0.33524E 01 -0.13854E 02 0.79975E 00 0.50000 28716E 01 0.86603E 00 -0.12075E 01 0.72054E 02 0.71450E 01 -0.23950E 01 0.72650E 00 0.50000 34482E 01 0.86603E 00 -0.12550E 01 0.7253E 02 0.41173E 01 -0.23950E 01 0.72650E 00 0.50000 46248E 01 0.86603E 00 -0.12624E 01 0.71777E 02 0.88513E 00 -0.27739E 01 0.79975E 00 0.50000	0 716166	-0.3636E-0-	0.115266.0	0 307071.	300010	2000	02675	
28716E 01 0.86603E 00 -0.12075E 01 0.72053E 02 0.71450E 01 -0.98800E 01 0.72650E 00 0.50000 0.41473E 01 0.23950E 01 0.72650E 00 0.50000 0.4248E 01 0.10000E 01 -0.12350E 01 0.77675E 02 0.41473E 01 -0.23759E 01 0.77675E 00 0.50000 0.4675E 01 0.50000E 01 0.79975E 00 0.50000	24289F 0	0.5000CF	0.11801F	718845	33656	244	799756	50000
34482E 01 0.10000E 01 -0.12350E 01 0.72533E 02 0.41173E 01 -0.23950E 01 0.72550E 00 0.50000 46248E 01 0.86603E 00 -0.12624E 01 0.71477E 02 0.85513E 00 -0.27739E 01 0.79975E 00 0.50000 4675E 01 0.50000F 00 -0.12898E 01 0.716789E 01 0.716789E 01 0.50000	28716E 0	0.86603E 0	0.12075E 0	.72053E 0	-71450F	100E	.72650E	50000E
46248E 01 0.86603E 00 -0.12624E 01 0.71477E 02 0.85513E 00 -0.27739E 01 0.79975E 00 0.50000	34482E 0	0.10000E 0	.12350E 0	.72533E 0	.41173E	50E	.72650E	. 50000E-
44675F 01 0.50000F 00 -0.12898F 01 0.11013F 02 0.14579F 00 -0.13192F 01 0.92475F 00 0.50000	4C248E 0	0.86603E 0	.12624E	.714776 0	.8551JE	39E	.79975E	- 50000E-

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NO. OF REV. OF WAKE = 4 DELTA PSI = 30.000 DEG. DeG. 2.620 = 12 1 = 1 STATIONS = 1 AZIMUTH 0F 00 0.14650E H ₹

NU. OF BLADES = .

PSI = 0. DEGREES

NUMBER

BLADE

1

0.277446 −01 0.70102E 02 0.18336E 00 −0.69979E 01 0.23744E 01 0.70102E 02 0.46531E 01 −0.59979E 01 0.59736E 02 0.59736E 01 0.59736E 02 0.597376E 01 0.597376E

0.50000E-01 0.50000E-01

STRENGTH

0.92675E 00
0.72650E 00
0.72650E 00
0.72650E 00
0.92675E 00
0.92675E 00
0.92675E 00
0.92675E 00
0.12735E 01

38

0.13791E-08
0.50000E-00

X -0.16000E 0.34645E 0.12492E 0.12492E 0.12492E 0.14024E 0.14024E 0.14024E 0.14024E 0.14024E 0.14024E 0.16024E 0.16024E 0.16034E 0.16034E

NC. OF REV. OF WAKE DELTA PSI = 30.000			1
			VZ -0.26322E 01 -0.57287E 01 -0.37500E 00 -0.10791E 02 -0.14795E 02
TY DISTRIBUTION ATIONS = 12 ALPHA T = 2.620 DEG.	REES	POINTS	VY 0.94072E 00 0.61400E 01 0.11034E 01 -0.32539E 01 -0.39297E 00
HELICOPIER WAKE VORTICITY DISTRIBUTION  NO. OF AZIMUTH STATIONS = 12  MU = 0.14650E 00 ALPHA T = 2.6	PSI = 0. DEGREES	VELOCITIES AT OTHER POLNTS	VX 0.67616E 02 0.65756E 02 0.64356E 02 0.7490E 02 0.75744E 02
HELICOPIER NO. C MU =, 0.14650E	PSI	VELOC	2 -0.40000E 00 -0.40000E 00 -0.40000E 00 -0.40000E 00
: 2		,	Y 0.3000CE 00 0.3000CE 00 0.3000CE 00 0.3000CE 00
NO. OF BLADES = 2 LAMBDA = 0.20900E-02			X -0.10000E 01 -0.50000E 00 0.0000E 00

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8660			7	×	>	۸۷	T.	וא ששט
	0	50000E	•	.71749E 0	14935E	7381E	.92675E	50000
0	<b>.</b>	-0.119736-03	-0.211656-01	0.71727E 02	-0.51437E-01	-0.16223E 02	0.10732E 01	0-50218E-01
7333	0	0.85714F	.43003E-	730596	101016	30000	120025	.502516
30.06	0	0.79540E	0.886086-	728765 0	2787F	1440F	12735	376067
11499	O	0.86503E	0.115916	.71837E 0	3047E	277E	12002F	50085
40501	0	0.50146E	0.14203E	.72245E 0	6341E	800E	.107326	50188
4698	0	0.58534E-	.16303E	.65080E 0	365LL	351E	.92675E	.49514E
25162	0	50194E	0.200346	.71617E 0	<b>6976</b> E	1209E	.79975E	• 49992E
6061	9 (	3684 VE	0.2/569E	.71132E 0	3835E	708E	.72650E	49939E
71017	2 0	310861	24/99E	.73609F 0	1981E	1284E	.72650E	49965E
1 28 70	<b>O</b>	370075	20000	. 12121 U	3639E	11/6	• 79975E	. 50110E
19986	0	17685E-	345 446	721216 0	7132E	3000	.92675E	501346
13417	0	0.43656F	0.37338F	725415 0	37611	3766	120021	100100.
16537	0	0.85841E	0.39683	.73802F 0	8469F	852F	127356	2007
12311	O	0.79944E	0.41602E	.74616E 0	6684E	539E	12735F	49988
80607	ဂ	37202E	0.45176E	.73228E 0	6686E	218E	.12002E	.49670E
51385	0	0.5c 4E	0.48162E	.70582E 0	5169E	600E	.10732E	49889E
44352	0	860E-	0.50274E	.66164E 0	2852E	.021E	-92675E	.49845E
9000	<b>O</b> C	00193E	0.53343E	.70318E 0	36418	442E	.79975E	.49808E
16207	0	37234E	5765E	. /2544E 0	9830E	,606E	. 72650E	49930E
22655	0	35931E	0.61262E	.72769E 0	05736	3505 1693F	799756	501406
27068	Ü	9701E	0.64485E	.71376E 0	6925E	505E	-92675E	50128
29169	0	0.74967E-	0.67375E	. 70719E 0	0089E	1655E	.10732E	.50153E
28605	o c	19704E	0.70213E	.71423E 0	6063E	662E	. 12002E	.50250E
21508	0	0.1000GE	745105	./3440F 0	3777E	701E	12735E	49963E
17264	0	0.87322E	0.78094F	13972F 0	6737F	22 A F	120025	325005.
14354	0	J.50297E	0.81230E	.72540E 0	8513E	9736	.10732E	498306
13774	ပ	7022E-	0.838996	. 71.971E 0	.7538E	420E	.92675E	.49874E
58841	0	0342E	0.86449E	.72191E 0	1948E	542E	.79975E	.49881E
26039	<b>O</b>	37000	0.38/12E	7/3006E 0	3/11/2	029E	- 72650E	5001 ZE
31836	0	16088E	0.34186E	71493F 0	5978F	2000	10021.	300048
35248	0	9861E	0.97089E	.70162F 0	2258F	35.0	92675E	30000
38352	0	0.21837E-	J.99851E	. 7009BE 0	6873E	691E	.10732E	500518
37781		0.49316E	0.10269E	. 70260E 0	5553E	3691	.12002E	.50197E
34304		16 18 7E	0-10544E	.71729E 0	7002E	430E	.12735E	. 50069E
30636		0.100106	0.10748E	.74104E 0	3910E	1854E	.12735E	.50054E
22552		307760	30.71.0	./36%3E U	1500E	744E	120025	.49767E
22373		82016-	7.11417E	0 326421	7 4 7 5	2000	.10/32E	.49815E
25076		0367E	11952	718476	30700	3610	. 426/5E	149865
1.1504		17384E	).12183E	72089E 0	1659E	124E	. 72650F	. 500236
35270		.0045E	J.12376E	.72514E 0	9842E	1946E	72650F	50012
41031		396991	J.12654E	71451F 0	2290E	1696	79975F	400007
45452		39100	J.12935E		)			,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,

HELICOPTER WAKE VORTICITY DISTRIBUTION

0.50006-01 0.49982E-01 0.49982E-01 0.49982E-01 0.50141E-01 0.50181E-01 0.50236E-01 0.50236E-01 0.50236E-01 0.50236E-01 0.50216E-01 NO. OF REV. OF WAKE = 4 DELTA PSI = 30.000 DEG. 0.10732E 01
0.72656E 00
0.72656E 00
0.72656E 00
0.72656E 00
0.72656E 00
0.72656E 00
0.12735E 01
0.12735E 01 0.476926 01 0.234796 01 0.234796 01 0.236126 01 0.236126 01 0.133206 02 0.155956 02 0.155956 02 0.133206 02 0.155956 02 0.155956 02 0.13456 01 0.13456 01 0.13456 01 0.13456 02 0.13456 02 0.13456 02 0.13456 02 0.13456 02 0.13456 02 0.13456 02 0.13456 01 0.13456 01 0.15206 02 0.13456 01 0.15206 02 0.13456 01 0.15206 01 0.15206 01 0.15206 01 0.15206 01 0.15206 01 0.15206 01 0.15206 01 0.15206 01 0.15206 01 0.15206 01 0.15206 01 0.15206 01 0.15206 01 0.15206 01 0.15206 01 0.15208 01 0.15208 01 0.15208 01 0.15208 01 0.15208 01 0.15208 01 0.15208 01 0.15208 01 0.15208 01 0.15208 01 0.15208 01 0.15208 01 0.15208 01 0.15208 01 0.15208 01 0.15208 01 ı DEG. 2.620 0.62964E-01
0.6578E 00
0.6672E 00
0.6578E 00
0.70128E 01
0.31496E 01
0.3178E 01
0.3178E 01
0.3178E 01
0.3178E 01
0.3269E 01
0.26231E 01
0.26313E 01 OF AZIMUTH STATIONS = 12 = 00 ALPHA T = DEGREES BLADE NUMBFR\_2 0.70464E 02 0.69828E 02 0.71832E 02 0.72614E 02 0.72514E 02 0.72516E 02 0.72516E 02 0.72646E 02 0.72646E 02 0.72646E 02 0.7266E 02 0.72793E 02 0.72794E 02 0.72793E 02 0.72796E 02 0.72796E 02 0.727976E 02 0.727976E 02 0.727976E 02 0.727976E 02 0.727976 30.000 NG. OF / -0.76579e-02 -0.84900e-01 -0.84900e-01 -0.84900e-01 -0.15202e-01 -0.15202e-01 -0.15202e-01 -0.25186e-00 -0.25186e-00 -0.25186e-00 -0.34605e-00 -0.34605e-00 -0.34605e-00 -0.34605e-00 -0.44139e-00 -0.53783e-00 -0.44141e-00 -0.53783e-00 -0.44141e-00 -0.53783e-00 -0.44141e-00 -0.53783e-00 -0.653789e-00 -0.6537899e-00 -0.653789e-00 -0.653789e-00 -0.653789e-00 -0.653789e-00 -0.6537899e-00 -0.653789e-00 -0.6537899e-00 -0.653789e-00 -0.6537 H ž -0.50000E 00 0.50120E-03 0.65051E 00 0.95356E 00 0.49536E 00 0.49638E 00 0.99865E 00 0.99865E 00 0.99865E 00 0.99865E 00 0.99965E 00 0.99966E 00 0.99 NO. OF BLADES = LAMBDA = 0.20900E-02 0.366034 0.3666034 0.3666034 0.3666034 0.369456 0.153866 0.153866 0.153866 0.275816 0.2 STAT

DISTRIBUTION	
VORTICITY	
WAKE	
HELICOPIER WAKE VORTICITY DISTRIBUTION	

NG. OF REV. UP WARE * 4 DELTA PSI * 30.000 DEG.			01 01 02
, DEG.			V2 -0.25451E 01 -0.5431E 01 -0.21935E 01 -0.95497E 01
NO. OF AZIMUTH STATIONS = 12 4650E 00 ALPHA 1 = 2.620 DEG.	ees	VELOCITIES AT OTHER POINTS	VY 0.11893E 01 0.64448E 01 -0.18212E 01 -0.14831E 01
= AZIMUTH STATI 30	PSI = 30.000 DEGREES	ITTES AT OTHER	VX 0.67669F 02 0.66366F 02 0.71123E 02 0.74233L 02
NO = 0.14650E 00	ISH	VELOC	2 -0.49000E 00 -0.40000E 00 -0.40000E 00 -0.40000E 00
: ;			Y 0.3000CE 0.3000CE 0.3000CE 0.3000CE 0.3000CE
NO. OF BLADES = 2 LAMBDA = 0.20300E-02			x -0.1000CE 01 -0.5C000E 07 0.5000E 00 0.1C00CF 01

NO. OF REV. OF WAKE # 4 DELTA PSI # 30.000 DEG.

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	S	190000	501456-	0000	499955	50079E-	717E-	49624E-	9971E-	0115E-	8491E-	49022E-	13166-	17416-	1252E-	3423E-	07355-	48149E-	1475E-	7754E~	-39665	98796-	8209E-	-36060	2662E-	5175-	4203E-	-36779	1995E-	3905E~	7724E-	7578E-	02015	77605	0-12610	2332E-	2484E-0	4054E-0	7292E-0	0160E-0	4936E-	<b>5658E-</b>	513E-	7131E-	49668E-	932E-	52615	1330E-	
	٠.	0 17325	2002F 01	0 10 3267	7735F 01 0	2002E 01 0	0732E 91 0	2675E 00 0	9975E 00 0	2650E 00 0	2650E 00 0	9975E 00 0	2675E 00 0	3732E 01 0	2002E 01 0	2735E 01 0	2735E DI0	2002E 01 0	3732E 01 (	2675E 00 (	9975E 00 (	2650E 00 (	2650E 00_ (	9975E 00	2675E 00 ,	3732E 01 (	2002E 01 (	2735E 01 (	27356 01	2002E 01	0732E 01	2675E 00 0	9975E 00 0		0. 799756	2675E 00 0	3732E 01 0	2002E 01 0	2735E 01 0	2735E 01 0	2002E 01 0	0732E 01 0	2675E 00	9975E 00	2650E 00 0	2650E 00 0	9975E 00 0	26,75E 00 0	
:	^^	300560	2000	30,011.0	0.234026	0.51412F	0.39787E	0.30235E	0.78051E	3287E	1.25280E	3562E	.16447E	1.17434E	).16454E	.22491E	1.21405E	.89212E	1.16°78E	1.18656E	12836€	3.74970E	0.13029E	0.11021E	0.14458E	3160E	0.16805E	0.148706	0.43267F	0.12540E	0.14466E	3924E	14005	0.360645	-0-14/64E UL	3190E	0.10246E	1177E	0.12122E	0.39168E	3409E	0.122886	4188E	10906	1362E	5 8 0 0 E	3428E	1699E	•
	<b>&gt;</b>	71406-	7005	200	2001	4.51F	5689E	5762E	3879C	3646E	3848E	2583E	7843E	3415E	5719E	921 <i>8</i> E-	8.7.79E	0972E	16796-	4011E	39092	4569E	2687E.	1407E	1260E	4974E	5460E	6311E	1351E	9961E	6847E	2771E	34345	37176	10 3460346.01	7127E-	5481E	3937E	11136	3187ō	2 is 8 2 E	4500E	4096E	1148F	8761E	0255E	78096-	6439E-	•0
BLADE NUMBER	>	719026	765346 0	740105	716625	71094F 0	. 70695E 0	.68613E 0	.71004E 0	. 709686 0	.70527E 0	.73121E 0	.72934E 0	.72505E 0	.72844E 0	.858736 0	.71577E 0	.75684F 0	.71007F 0	.67848E 0	.70387E 0	.13503E 0	•69957E 0	.73802E 0	.70579E 0	.70258F 0	.70299E 0	.72158E 0	.72550C O	. 76732E 0	. 147446 0	.7310 JE 0	0 486787.	73,7065	0.72326E CZ	692401	.67545E 0	. 68917E D	.698C2E 0	.73224E 0	.75547E 0	.74107F 0	.73184E 0	.72733E 0	.73123E 0	.71752E 0	.70705£ 0	.7C521E 0	•0
	,		7007	-340045	0.724016	0.7202F-	305446-	0.22989E-0	0.30863E-0	0.366996-0	. 33340E-0	0.14989E 0	.20575E C	.23645E 0	0.27565E 0	0.295376 0	,30956E-0	0.18214F C	0.187906 0	0.126596 0	0.16758E 0	100726 0	0.87670E-0	0.30988E 0	0.36539E C	.41499E 0	.46937E C	0.43695E 0	.17486E 0	0.23992E 0	.47129E C	0.47039E C	.47752E U	0 110616.0	-0.55335E 00	0.640C6E 0	0.69222E G	0.75332E 0	.74126E 0	.51206E 0	.66587E 0	.81858E O	0.35018E 0	.41442E G	.68925F C	.58146E 0	.82672E C	7786E C	.31033E C
	>		0.131929	0.40740	370666	0 86523E	0.503235	0.28829E-	.50627E	.96792E	.96077E	87845E	.47373E	-32006E-	-45874E	0.93812E	. 33281E	0.32083E	0.510276	0.46315E-	.51632E	.73065E	.80302E	.90357E	.44315E	-33634E-	.42956E	C-7305CE	0.90838E	.10027E	.53207E	.96237E-	.563448	100045	0.127225 00	45004E	-14937E-	0.44813E	.76257E	0.37206E	.1022CE	.57754E	.1730CE-	.59772E	.10224E	.76182E	.73772E	.46336E	.14663E-
	•	, d	100001	0 367747.	ט ט ס	0 364467-0	0 481876	54709F O	0.32817F 0	113766 0	698181 O	.12980E	.17409F 0	.1315F 0	.13025E 0	.16935E 0	.11802E 0	3.7777E 0	.48676E 0	.43485E 0	.53541E 0	.10733E	.16447E 0	.22465E 0	.26690E 0	.28738E 0	.28235€	.256575	.21526€	.17722E	.14308E	.131835	.1549CF	1482077	2161	357435	387778.	.37223E	.34755c	.30934∄	.26850E	.23474E	.22484E	.24863E	.295836	.35460E	.4C618L	.44787E	.46853F
	CTAT	1	(	7 1	η,	; r'u	٠ ٧	o <b>~</b>	- α	o 0	_		17	13	<b>51</b>	15	9	7	81	19	20	21	22	23	<b>5</b> 7	52	92	27	28	53	ရှိ	31	32		\$ C	98	37	98	39	704	41	45	43	7,7	45	94	47	48	49

HELICOPTER MAKE VORTICITY DISTRIBUTION

Man manager man defendance a similar de de		TIV BOOD HIONBO	2675F 00 0.50000	9975E 00 0.49987E	2650E 00 0.50006E	2650E 00 0.49687E	9975E 00 0.49701E	2675E 00 0.50743E	0732E 01 0.51027E	2002E 01 0.50788E	2133E 01 0.4888E	2002E 01 0.50642E	0732E 0; 0.50902E	2675E 00 0.47791E	99973E 00 0.48448E	2630E 00 0.30194E	3975E 00 0.48914E	2675E 00 0.51776E	0732E 01 0.52217E	2002E 01 0.52648E	2735E 01 0.51403E	2002E 01 0.45373E	0732E 01 0.50510E	26/3E UU U.4/234E 9975E OO 0.44278E	2650E 00 0.50460E	2650E 00 0.48038E-0	9975E 00 0.51636E-0	0732E 01 0.52986E-0	2002E 01 0.54372E-0	2735E 01 0	2002F 01 0.44393F-0	0732E 01 0.44697E	2675E 00 0.44273E	34505 00 0.45807E	2650E 00 0.49549E	9975E 00 0.52092E	2675E 00 0.51912E	732£ 01 0.51941E	27365 01 0 232335 27365 01 0 483436	2735E 01 0.50411E	2002E 01 0.44942E
		ī	78 7340F 01 0.5	1369E 01 0.7	1472E 01 0.1	0.26045E 01 0.7	0.22397E 02 0.7	0.18256E 02 0.9	0.18078E 02 0.1	1901E 02 0.1	0.13382E 02 0.10	1276E 02 0.1	0.115316 02 0.1	0.32198E 01 0.9	0.10546E 02 0.7	0.566616 01 0.56660	0.117096 01 0.7	0.15517E 02 0.9	0.16588E 02 0.1	0.18286E 02 0.1	0.52760E 01 0.1	960E 01 0.1	0.167526 02 0.1	712E 02 0.5	0.63567E 01 0.7	0.40697E 01 0.7	1929E 02 0.7	0.13097E 02 0.1	0.15062E 02 0.1	0.14851E 02 0.1	1411E 01 0.1	0.12761E 02 0.1	0.16678E 02 0.9	359E 02 0.1	0.10520E 01 0.7	0.73583E 01 0.7	0.71663E 01, 0.9	0.66756E 01 0.1	0 10 01 00 00 00 00 00 00 00 00 00 00 00	0.31840E 01 0.1	135E 01 3.1
GREES	2,	2	**************************************	.63036E 0	.45596E-0	.22705E.0	.20262E 0	.17137E 0	.39721E 0	.24701E 0	0 391705	5 38912 0	.283856 0	,82527E 0	0-314824.	120068 0	-52459E C	.42523E 0	.60505E 0	.11709E 0	0.69580E 0	.78160E 0	.24048E 0	.3313/E 0	.35311E 0	. BLOORE O	.35651E 0	.51129E 0	.90574E 0	0.79967# 00	0 366954	.44328E 0	.10146E 0	.53305E 0	.46900E 0	0.24461E 0	.24425E 0	.16432E-0	0-365101.	.33111E 0	.62990E 0
I = 720.000 DEG	BLADE NUMBER	2	,67474F 0	.63387E 0	.70762F 0	• 70829E Q	.75061E 0	.73448E 0	. 73359E 0	• 73938E 0	720825 0	.72106E 0	.716971 0	0 469642	.70329E 0	0 369671	.75496F O	.71732E 0	.71881E 0	. 72128E 0	.71740E 0	764861 0	0 36156	. 71215E O	.73582E 0	. 70868E 0	.71324E 0	.69492E 0	.69194F 0	0.71817E 02	15793E 0	.74131E 0	.71438E 0	.73264E 0	.72091E 0	. 70050E 0	.69737E C	.70166E 0	0 04040	.72358E 0	.75043E 0
		•	7 70	.63355E-0	.76117E-0	-67468E-0	0.51141E-U	0.10350F C	0.12459E 0	. 15336E C	0.220076-0	0.83521E-0	0.105736 0	.53032E-0	0.35090E-0	0-100185-0	0.21977E G	.23756F 0	0.33253E 0	0.386356 0	.43529E-0	0.23386E 0	0.29600E 0	0.24073E O	0.91255E-0	0.96509E-0	0.39330E 0	0.55546E 0	0.61658E 0	-0.59064E 00	0.47857E 0	0.63960E 0	0.699076 0	.64157E 0	0.41896E 0	0.70398E 0	0.77051E 0	0.81277E 0	0 362600.0	.67607E 0	0.841715 0
	-	;	1351CE-	56E	.36643E	.93625E	.85568E	.48478E	0.16138E-	*04E	0.034436	0.8711CF	.51915E	0.43672E-	.51046E	366026	. 30 30 SE	.463U2E	0.423906-	.44778E	0.875476	G. 17636E	C. 50357E	0.30437E- 0.53701E	. 29130E	30 3E	. 75808E	.28497E-	.43832E	-0.74627E 00	1008CE	0.55163E	-19016E-	1.15E	.94413E	.78429E	.45829E	0.21168E-	777016	0.10155E	.10349E
	ı	•	, 1000c	.78345F	.34553F	.232271	36 3518.	.12675F	14778	.1 /35E	708695	235010	.83860E-	.76713E-	192961	116475	18025F	.22100F	.24234€	,23732F	16576F	2774F	.96435E	107496	.15712E	.21378F	.26981F	.33314E	.32760E	0.362956 01	. 2222E	39€181.	.16176E	.20144E	.30898E	.35118E	.40241E	.42299E	361114.	5512E	.31465E
			: -	2	٣.	3	Ş	91	~ (	<b></b>	<u>, 5</u>	2	12	13	<b>5</b> 1	2 2	17	18	61	0.7 	22	23	24	5.7 2.7	27	. 58	£3 \$	31	32	33	35	36	37	9 9	, o,	41	45	4 4 6 4	57	46	1.4

	NO. OF REV. OF WAKE = 4 DELTA PSI = 30.000 DEG.								
	1			7.4	-0.29231E 01	-0.66757E 01	-0.68770E 01	-0.84857E 01	-0.126836 02
DISTRIBUTION	IIONS = 12	REES	POINTS	*	0.80046E 00	0.55386E 01	-0.21054E 01	0.227326 01	0.504098 01
HELICOPTER WAKE VORTICITY DISTRIBUTION	AZIMUTH STAI	PSI = 720.000 DEGREES	VELOCITIES AT OTHER POINTS	×	0.672536 02	0.66243F 02	0.70195E 02	0.54424E 02	0.64762E 02
HEL ICOP TER	NO. OF WO. OF WO. OF WO. OF WO.	PS	VELO	7	-0.40000E 0G	-0.40000E CC	-0.40000E 00	-0.40000E 00	-0.40000E CO
	: 2 12				0.3000CE 00	0.3000CE	0.3000CE	00.3000CE 00	0.3000CE
	NO. OF 3LADES = 2 DA = 0.20900E-02			×	-0.1000CE 01	-0.5000F 00	•	0.50000£ 00	C.13030E 01

TABULATION OF SURFACE-ELEMENT VERTEX COORDINATES FOR A UH-IB FUSELAGE

ELEMENT No.			1							~		
m	× <sub>1m</sub>	41m	31m	$x_{2m}$	Y2m	32m	$x_{3m}$	43m	33m	$x_{4m}$	Yum	34m
I	5!9	.019	425	519	.013	378	519	0	376	519	0	425
2	519	.042	422	519	.032	382	519	.013	378	519	.019	425
3	519	.049	414	519	.049	403	519	.032	382	519	.042	422
ц	498	0	452	498	.038	448	519	.019	425	519	0	425
5	498	.038	448	498	.076	437	519	.042	422	519	.019	425
6	498	.076	437	498	.091	422	519	.049	414	519	.042	422
7	498	.091	422	498	.097	399	519	.049	403	519	.049	414
8	498	.097	399	498	.057	363	519	.032	382	519	.049	403
9	498	.057	363	498	025ء	351	519	.013	378	519	.032	382
10	Ļ98	.025	351	498	0	346	519	0	376	519	.013	378
11	445	0	469	445	.051	463	498	.038	448	498	0	452
12	445	ا 05،	463	445	. 106	448	498	.076	437	498	.038	448
13	445	. 106	448	445	.129	427	498	.091	422	498	.076	437
14	445	. 129	427	445	.133	397	498	.097	399	498	.091	422
15	445	. 133	397	445	.083	340	498	.057	- 363	498	.097	~.399
16	445	.083	340	445	.036	325	498	.025	351	498	.057	363
17	445	.036	325	445	0	323	498	0	346	498	025	351
31	405	0	47!	405	.051	~.467	445	.051	463	445	0	469
19	405	.051	467	405	110	452	1	106	448	445	.051	463
20	~.405	.110	452	405	. 136	429	445	.129	427	445	. 106	448
21	405	. 136	429	405	. 148	399	445	1.133	397	445	1.129	427
22	405	.148	399	405	. 123	340		.083	340	445	. 133	397
23	405	. 123	340	405	.095	302	445	.036	325	445	.083	340
24	405	.095	302	1	.078	289	445	.027	325	445	.036	325
25	405	.078	-,289	ł	.061	281	445	.019	323	445	.027	325
26	405	.061	28 1	405	.027	279	445	.008	1323	~.445	.019	323
27	405	.027	279	405	0	278	~.445	0	323	,445	.008	323
28	366	0	47 1	366	.053	471	405	.051	467	405	0	471
29	366	.053	471	366	.114	456	405	.110	452	405	.051	467
30	366	. 114	-,456	366	.140	433		. 136	429	405	.110	452
31	366	. 140	433	!	. 153	3110	il .	148	399	405	. 136	
32	366	. 153	404	1)	.134	340 287	11	.123	340	405 405	123	399
34	366	.129	287	11	.117	261	11	.078	289	405	.123	302
35	366	.117	261	366	.097	245	11	.061	281	405	.078	289
36	366	.097	245	ii	.045	230	18	.027	279	- 405	.061	281
37	366	.045	~.230	11	0	228	405	0	278	405	.027	279
38	294	0	471	294	.053	471	13	.053	471	366	0	471
39	294	.053	-,471	294	.114	458	11	.114	- 456	- 366	.053	471
40	294	1114	458	294	. 140	437	11	.140	433	- 366	.114	456
41	294	. 140	437	12	. 155	406	11	. 153	404	366	.140	433
42	294	. 155	406	294	. 142	340	11	. 134	340	366	. 153	404
43	294	. 142	340		. 136	285	11	. 129	287	364	. 154	340
44	294	. 136	285	"1	. 133	255	ll.	.117	261	366	. 129	287
45	294	. 133	255	11	.110	230	11	.097	245	366	.117	261

# TABULATION OF SURFACE-ELEMENT VERTEX COORDINATES FOR A UH-IB FUSELAGE (Cont'd)

ELEMENT No.	γ.			~			4			2.		
m	× <sub>1m</sub>	YIm	31m	$x_{2m}$	Y2m	32m	1/3m	¥3m	33m	X4m	44m	3+m
46	294	.110	230	294	.051	219	366	.045	230	366	.097	245
47	294	.051	219	294	0	217	366	0	228	366	.045	230
48	217	0	471	217	.053	471	294	.053	471	294	0	471
49 50	217	.053	471 461	217 217	.117	461 440	294	.114	458 437	294	.053	471 458
51	217	.148	440	217	. 159	408	294	. 155	406	294	.140	437
52	217	. 159	408	217	. 155	340	294	.142	340	294	. 155	406
53	217	. 155	340	217	. 150	279	294	. 136	285	294	.142	-,340
54	217	. 150	279	217	. 144	247	294	. 133	255	294	.136	285
55	217	. 144	~.247	217	.121	221	294	.110	230	294	. 133	255
56	217	.121	~.221	217	.055	209	294	.051	219	294	.110	230
57	217	.055	209	217	0	209	294	0	217	294	.051	219
58	084	0	471	084	.053	471	217	.053	471	217	0	471
59	084	.053	471	084	.121	467	217	1117	461	217	.053	471
60	084	.121	467	084	. 159	-,452	217	. 148	440	217	.117	461
61	084 084	.159	452 420	084 084	, 178 , 178	420	217 217	. 159	408 340	217 217	. 148	440
63	084	.178	340	084	. 170	270	217	. 150	279	217	. 155	340
64	084	. 170	270	084	.161	236	217	. 144	247	217	. 150	279
65	084	. 161	236	084	.125	217	217	.121	221	217	. 144	247
66	084	. 125	-,217	084	.055	209	217	.055	209	217	.121	221
67	084	.055	209	084	0	209	217	0	209	217	.055	209
68	.066	0	471	.066	.053	471	084	.053	471	084	0	471
69	.066	.053	471	.066	. 144	458	084	. 121	467	084	.053	471
70	.066	.114	458	.066	. 138	439	084	. 159	452	Ť	.121	467
71	.066	. 138	439	.066	. 152	408	084	. 178	420	084	. 159	452
72	.066	.152	408 340	.066	.150	340 283	084	. 178	340 270	084 084	. 178	420 340
74	.066	.142	283	.066	.127	259	084	. 161	236	084	. 170	270
75	.066	. 127	259	.066	.098	242	084	. 125	217	084	. 161	- 236
76	.066	.098	242	.066	.053	232		.055	209	1	. 125	217
77	.066	.053	232	.066	0	230	084	0	209	084	.055	209
78	.241	0	444	.241	.038	433	.066	.053	471	.066	0	471
79	.241	.038	433	.241	.057	403	.066	.114	458	I	.053	471
80	.241	.057	403	.241	.061	384	i	. 138	439	1	.114	458
81	.241	.061	384	.241	.062	368	.066	. 152	408	I	.138	439
82	.241	.062	368	.241	.061	340	.066	. 150	340		. 152	408
83 84	.241	.061	340	.241	.053	317 310	1	.142	283 259	l P	.150	340 283
85	.241	.049	310	.241	.040	298	.066	.098	242		.127	259
86	.241	.040	298	.241	.021	291	.066	.053	232	I .	.098	242
87	. 241	.021	291	.241	0	289	8	0	230		.053	232
88	.269	0	410	. 269	.025	401	.241	.038	433		0	444
89	.269	.025	401	.269	.030	368	.241	.057	403	4	.038	433
90	.269	.030	368	.269	.028	353	.241	.061	384	.241	.057	403

# TABULATION OF SURFACE-ELEMENT VERTEX COORDINATES FOR A UH-IB FUSELAGE (Cont'd)

ELEMENT No.	× <sub>Im</sub>	Yım	31m	¥2m	42m	32m	V <sub>3m</sub>	43m	33m	164m	94m	34m
91	. 269	.028	353	. 269	.019	333	.241	.061	340	. 241	.062	368
92	.269	.019	333	.269	.011	329	.241	.049	~.310	. 241	.053	317
93	.269	.011	329	.269	.006	327	.241	.021	291	. 241	.040	298
94	. 269	.006	327	.269	0	327	.241	0	289	. 241	.021	291
95	.269	0	327	. 269	.019	333	.269	.025	401	.269	0	410
96	.269	.019	333	.269	.028	368	.269	.030	368	.269	.025	401

# REFERENCES

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### APPENDIX I

### OPERATIONAL INFORMATION FOR THE MAIN PROGRAM

This program is written in FORTRAN IV, with the exception of subroutine CLEAR, which is written in MAP. This routine is used to initialize storages to be zero.

### **INPUTS**

CARD 1

NB:

Number of blades,  $N_A$ 

NRW:

Number of Revolutions of wake per blade, NR

NA:

Number of azimuth stations, Ne

NPNCH:

Punch option. If zero, no cards are

punched at the end of a run. If not zero, all wake point coordinates and core sizes at the final azimuth position are punched

on cards.

NOPT:

If zero, the initial wake configuration is

computed. If not zero, initial wake

configuration is read in.

NTAPE:

If not zero, wake point coordinates and velocities are saved on utility Tape 4.

NPRINT:

If NPRINT = 1, coordinates and velocities

for each wake point are printed; if

NPRINT = 2, those for every other point

are printed; if 3, every third; etc.

LNCT:

Number of lines desired per page of output.

NFPT:

Number of fuselage points, N<sub>f</sub>

NXPT:

Number of points off the wake for which

velocities are to be calculated.

NPINT:

Output is produced at intervals of NPINT

steps; i. e., if NPINT = 1, the data for

each azimuth position is printed.

CARD 2

PSIO:

Initial position of blade 1,  $\psi_{init}$  , degrees.

REV:

Number of revolutions of rotor for which

calculations are to be performed, NRY

XLAM:

ג

XMU:

μ

ALPHAT:

 $\alpha_r$  (degrees)

FACTR:

Factor applied to  $V_{3,\infty}$ ,  $K_f$ 

RB:

R/b

CARD 3, 4,

GAMB:

Strengths of blade 1; NA of them.

Al:

Core sizes at Blade 1; (NA of them).

**A**:

Initial core sizes; (NRW)(NA)(NB) of them.

Fuselage Data: Four cards for each point; (4)(NFPT) cards in all.

These are punched by the Fuselage Program.

Card 1	XBAR ≅	YBAR <b></b>	ZBAR \$	SIGX $O_{\chi}$	SIGZ $\sigma_{3}$	
Card 2	XII	XI2	XI3	XI4	ETAl	ETA2
	E <sub>I</sub>	<b>E</b> 2	<i>ξ<sub>3</sub></i>	<i>ξ</i> 4.	11	72
Card 3	ETA3	ETA4	Dl	D2	D3	D4
	73	<b>7</b> ≁	d,	d <sub>2</sub>	d <sub>3</sub>	&≠
Card 4	$^{\rm XLE}_{\lambda_{7}}$	XME µη	XNE ック	XLZ $\lambda_{\zeta}$	XMZ μς	XNZ

Coordinates of points off the wake at which velocities are to be computed NXPT points in all (up to three sets of coordinates per cord):

TELK

TIPT

ZIPT

7Ú

 $\mathcal{G}_{-}$ 

3

Initial Wake Configuration - Read in only if NOPT is not zero.

X:

(NRW)(NB)(NA) of them.

**Y**:

(NRW)(NB)(NA) of them.

Z:

(NRW)(NB)(NA) of them.

A listing of the program is given on the pages which follow.

```
$IBFTC ZZHWV LIST, REF
      CALCULATION OF THE WAKE VORTICITY DISTRIBUTION FOR A HELICOPTER
      COMMON X(340,4),Y(340,4),Z(340,4),U(340,4),V(340,4),W(340,4),
            GAMA(340,4), SEG(340,4), GAMB1(100), A1(100), A(340,4), PI, RAD,
             YMP, XMCL, XMSL, NB, NRH, NA, NW, NOPT, NTAPE, NPRINT, NDVCH, PSIO,
     2
             XHU, XLAH, ALPHAT, PINT, PSIF, XNA, DPSI, NB1, NW1, XNW, XNB, TPNB,
             SAT, CAT, C1, C2, PSI, TPI, XI, T1, T2, XJ, NPS, JPS, IPS, IPS1, XXX, YYY,
     4
             ZZZ, IST, IND, IFLG, SIG1, SIG2, SIG3, GGG, DEN, XNU1, XNU2, XNU3, IR1,
             XMX,XMY,XMZ,SIG4,SIG5,RR,SQI1,SF,SQI,SG,BF,LPS,SEG1,SEG2,
     6
            SUM, LNCT, XIPT(400), YIPT(400), ZIPT(400), VX(400), VY(400),
     _7_
             VZ(400), VXF(400), VYF(400), VZF(400), NXPT, NAB, FACTR, RB
     8
      COMMON /FUSE/ XBAR(100), YBAR(100), ZBAR(100), SIGX(100), SIGZ(100),
             XI1(100), XI2(100), XI3(100), XI4(100), ETA1(100), ETA2(100),
             ETA3(100), ETA4(100), XLE(100), XME(100), XKE(100), XLZ(100),
             XXZ(100), XNZ(100), NFPT, RJ(4), EJ(4), HJ(4), EMJ(4), D1(100),
     3
             D2(100),D3(100),D4(100),VXINF,VYINF,VZINF,UF,VF,WF

    DIMENSION GAMB(100)

      EQUIVALENCE (GAMB1, GAMB)
    1 CALL CLEAR (X, NAB)
      CALL CLEAR (XBAR, WF)
      PI = 3.1415926536
      RAD = .0174532925
      TPI = 2.0*PI
  READ 1000, NB, NRW, NA, NPNCH, NOPT, NTAPE, NPRINT, LNCT, NFPT, NXPT, NPINT,
                NDVCH
1000 FORMAT(1216)
      CALL DVDCHK(NDVCH)
      IF(NTAPE LT.O) REWIND 4
      READ 1001, PSIO, REV, XLAM, XMU, ALPHAT, FACTR, RB
1001 FORMAT(9F8.6)
      READ 1001, (GAMB1(I), I=1, NA)
      READ 1001_{1}(A1(I), I=1, NA)
      NB1 = NB
      NW = NRW*NA
      NW1 = NW+1
      NAB = NB*NA
      XNA = NA
      DPSI = 2.0*PI/XNA
      XNW = NW
      XNB = NB
      SAT = SIN(ALPHAI*RAD)
      CAT = COS(ALPHAT*RAD)
      C1 = XMU*CAT
      C2 = (XMU*SAT+XLAM)
      C3 = XMU+SAT+SQRT(XLAM+XNB/2.0)
      XMCL = C1/XLAM
      XMSL = XMU*SAT/XLAM
      VXINF = XMCL
      VZINF = -FACTR*(XMSL+SQRT(.5*XNB/XLAM))
      TMP = RB*DPSI
      TMP1 = SQRT(TMP*(TMP+2.0))
      FRB = (TMP-TMP1+ALOG(1.0+TMP+TMP1))/DPSI
      READ 1001, ((A(I,J), I=1,NW), J=1, NB1)
      IF(NFPT.EQ.O) GU TO 100
      READ 1003, (XBAR(I), YBAR(I), ZBAR(I), SIGX(I), SIGZ(I), BLNK, XII(I),
       XI2(1),XI3(1),XI4(1),ETA1(1),ETA2(1),ETA3(1),ETA4(1),
```

```
2
             D1(I),D2(I),D3(I),D4(I),XLE(I),XME(I),XNE(I),XLZ(I),
            XXZ(1), XNZ(1), I=1,NFPT)
1003 FORMAT(6E12.5)
100 IF(NXPT-EQ.0) GO TO 103
    READ 1001, (XIPT(I), YIPT(I), ZIPT(I), I=1, NXPT)
101 00 102 f=1.NXPT
    CALL FUSLGE(X1PT(1), Y1PT(1), Z1PT(1), VXF(1), VYF(1), VZF(1))
102 CONTINUE
103 PSIF = PSI0+360.0*REV
    CALL IDOUT
    NCT = 0
   TPNB = 2.0 \cdot PI/XNB
    PSI = PSIO*RAD
    PSIO = PSI
    PSIF = PSIF*RAD*0.05
    IF(NOPT.EQ.O) GO TO 3
  2 READ 1003, ((X(I,J), I=1,NW1), J=1,NB)
  READ 1003.((Y(I,J),I=1,NM1),J=1,NB)
    READ 1003, ((Z(I,J), I=1, NW1), J=1, NB)
    GO TO 7
  3 DO 6 I=1,NW1
  XI = FLOAT(I-1) * DPSI
    T1 = XI * CI
   J3 = XI * C3
  4 DO 5 J=1,NB
    XJ = FLOAT(J-1)*TPNB
    X(I,J) = COS(PSIO+XJ-XI)+T1
   Y(I_{\bullet}J) = SIN(PSIO+XJ-XI)
    Z(1,J) = -T3
  5 CONTINUE
  6 CONTINUE
  7 NPS = AMOD(PSI0,2.0*PI)/DPSI+1.5
    IF (NPS.GT.NA) NPS = 1
   DO 9 J=1,NB
    JPS = MOD(NPS+(NA*(J-1))/NB+NAB,NA)
    IF (JPS.EQ.O) JPS = NA
    IPS1 = JPS
    DO 8 I=1.NW
    IPS = IPS1
    IPS1 = IPS-1
    IF(IPS1.EQ.O) IPS1 = NA
   GAMA(I,J) = (GAMB(IPS) + GAMB(IPS1))/2.0
  8 CONTINUE
  9 CONTINUE
  10 DO 12 J=1,NB1
  .DO 11 I=1,NW
    SEG(I,J) = SQRT((X(I,J)-X(I+1,J))**2*(Y(I,J)-Y(I+1,J))**2*(Z(I,J)-
            Z(I+1,J))++2)
  11 CONTINUE
 12 CONTINUE
 · 13 DO 29 I=1,NW
    DO 28 J=1;NB1
    XXX = X(I,J)
   V = V(I,I)
    ZZZ = Z(I,J)
   U(I_{\bullet}J) = 0.0
```

```
V(1,J) = 0.0
             W(I,J) = 0.0
      14 DO 25 L=1,NB1
             IST = 1
             IND = NW
             IFLG = 1
             IF (L.NE.J) GO TO 16
IND = I-2
             IFLG \approx 2
             IF (IND.GT.O) GO TO 16
      15 IST = 1+1
             IND = NW
             IFLG = 1
           IF (IST.GT.NW) GO TO 18
      16 SIG2 = SQRT((XXX-X(IST,L))**2+(YYY-Y(IST,L))**2+(ZZZ-Z(IST,L))**2)
             DO 17 IR=IST, IND
             SIG1 = SIG2
             SIG2 = SQRT((XXX-X(IR+1,L))**2+(YYY-Y(IR+1,L))**2+(ZZZ-Z(IR+1,L))
                           **2)
            SEGSQ = SEG(IR,L)**2
             HM1 = SIG1**2+SIG2**2
             IF(HM1.GT.SEGSQ)GO TO 160
             HM2 = .25*((SIG1+SIG2)**2-SEGSQ)*(SEGSQ-(SIG1-SIG2)**2)/SEGSQ
             IF(HM2.GT.A(IR,L)**2)GO TO 160
             GGG = GAMA(IR,L)/SEG(IR,L)
             GO TU 161
    160 GGG = GAMA(IR,L)*(SIG1+SIG2)/(SIG1*SIG2*((SIG1+SIG2)**2-SEGSQ))
  161 \times NU1 = (YYY-Y(IR+1,L))*(Z(IR,L)-Z(IR+1,L))-(ZZZ-Z(IR+1,L))*
           1
                              \{Y(IR,L)-Y(IR+1,L)\}
             XNU2 = (ZZZ-Z(IR+1,L))*(X(IR,L)-X(IR+1,L))-(XXX-X(IR+1,L))*
                            \{Z(IR,L)-Z(IR+1,L)\}
           1
            XNU3 = (XXX-X(IR+1,L))*(Y(IR,L)-Y(IR+1,L))-(YYY-Y(IR+1,L))*
                            (X(IR,L)-X(IR+1;L))
           1
             U(I_*J) = U(I_2J) + XNU1 * GGG
             V(I,J) = V(I,J) + XNU2 * GGG
             W(I,J) = W(I,J) + XNU3 + GGG
      17 CONTINUE
          _GO TU (18,15), IFLG
      18 IF (L.NE.J) GO TO 25
             IR1 = I-1
             IF (I.EQ.1) IR1 = 1
             XMX = (Y(IR1,L)-Y(IR1+1,L))*(Z(IR1+1,L)-Z(IR1+2,L))-(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+1,L)-Z(IR1+2,L))*(Y(IR1+2,L)-Z(IR1+2,L))*(Y(IR1+2,L)-Z(IR1+2,L))*(Y(IR1+2,L)-Z(IR1+2,L))*(Y(IR1+2,L)-Z(IR1+2,L))*(Y(IR1+2,L)-Z(IR1+2,L))*(Y(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1+2,L)-Z(IR1
                         Y(IR1+2,L))*(Z(IR1,L)-Z(IR1+1,L))
    XMY = (Z(IR1,L)-Z(IR1+1,L))*(X(IR1+1,L)-X(IR1+2,L))-(Z(IR1+1,L)-
                         Z(IR1+2,L))*(X(IR1,L)-X(IR1+1,L))
           XMZ = (X(IR1,L)-X(IR1+1,L))*(Y(IR1+1,L)-Y(IR1+2,L))-(X(IR1+1,L)-
                         X(IR1+2,L))*(Y(IR1,L)-Y(IR1+1,L))
           1
           SIG4 = SEG(IR1+1,L)
             SIG3 = SEG(IR1,L)
          SIG5 = SQRI((X(IR1+2,L)-X(IR1,L))**2+(Y(IR1+2,L)-Y(IR1,L))**2+
                            (Z(IR1+2,L)-Z(IR1,L))**2)
            SIG5-SIG4)
           1
             IF (DEN.EQ.0.0) GO TO 25
             IF(DEN.LT.0.0)WRITE(6,1002)I,J,SIG3,SIG4,SIG5
 1002 FORMAT(2X43HDENUMINATOR NEGATIVE FOR R COMPUTATION I = 13,3X3HJ =
```

```
13,3X6HSIG3 =E16.8,3X6HSIG4 =E16.8,3X6HSIG5 =E16.8 )
     RR = SIG3*SIG4*SIG5/SQRT(ABS(DEN))
     SQI1 = SQRT((2.0*RR-SIG3)*(2.0*RR+SIG3))
     IF (SIG3**2.LE.SIG4**2+SIG5**2) GO TO 19
     SF = (2.0*RR+SQI1)/SIG3
     GO TO 20
  19 SF = (2.0*RR-SQI1)/SIG3
     IF(SF \cdot EQ \cdot O \cdot O) SF = 1.0E - 20
  20 \text{ SQI} = \text{SQRT}((2.0 + \text{RR} - \text{SIG4}) + (2.0 + \text{RR} + \text{SIG4}))
     IF (SIG4**2.LE.SIG3**2+SIG5**2) GO TO 21
     SG = (2.0*RR+SQI)/SIG4
     GO TO 22
  21 SG = (2.0*RR-SQI)/SIG4
     [IF(SG-EQ.0.0)]SG = 1.0E-20
  22 IF (I.EQ.1) GO TO 23
     BF = (GAMA(IR1,J)*(ALOG(8.0*SF/A(IR1,J))+.25)+GAMA(I,J)*(ALOG(8.0*
            SG/A(I,J))+.25))/(4.0*RR*SQRT(XMX**2+XMY**2+XMZ**2))
  23 BF = (GAMA(I,J)*(ALOG(8.0*SF/A(I,J))+.25))/(4.0*RR*SQRT(XMX**2*))
          XMY * # 2 + XMZ * # 2 ) )
  24 U(I,J) = U(I,J) + XMX * BF
     V(I,J) = V(I,J)+XMY*BF
     W(I_*J) = W(I_*J) + XMZ + BF
  25 CONTINUE
     SIG1 = SQRT(XXX**2+YYY**2+ZZZ**2)
____26_D0_27_ L=1,NB
     LPS = MOD(NPS+(NA*(L-1))/NB+NAB,NA)
     IF(LPS \cdot EQ \cdot O) LPS = NA
     IF(I.EQ.1.AND.L.EQ.J)GO TO 260
     PSIBK = FLOAT(LPS-1)*DPSI
     SINPSI = SIN(PSIBK)
     COSPSI = COS(PSIBK)
     RMH2 = (XXX-COSPSI)**2+(YYY-SINPSI)**2+ZZZ**2
     IF (RMH2+SIG1**2.GT.1.0) GO TO 258
     RMH = SQRT(RMH2)
     H2 = .25*((SIG1+RMH)**2-1.0)*(1.0-(SIG1-RMH)**2)
     IF (H2*RB**2.GT.1.0) GO TO 258
     HH = SQRT(H2)
     XHT = XXX*(COSPSI**2+SINPSI**2/(HH*RB))-YYY*SINPSI*COSPSI*(1.0/
            (HH*RB)-1.0)
     YHT = YYY*(SINPSI**2+COSPSI**2/(HH*RB))-XXX*SINPSI*COSPSI*(1.0/
            (HH * RB) - 1.0)
     ZHT = ZZZ/(HH*RB)
     XNUI = -YHT*Z(1,L)+ZHT*Y(1,L)
     XNU2 = -ZHT*X(1,L)*XHT*Z(1,L)
     XNU3 = -XHT*Y(1,L)+YHT*X(1,L)
     SIG2 = SQRT((XHT-X(1,L))**2+(YHT-Y(1,L))**2+(ZHT-Z(1,L))**2)
     GO TO 259
 258 \text{ XNU1} = -YYY*Z(1,L)+ZZZ*Y(1,L)
   XNU2 = -ZZZ*X(1,L)+XXX*Z(1,L)
     XNU3 = -XXX*Y(1,L)+YYY*X(1,L)
     SIG2 = SQRT((XXX-X(1,L))**2+(YYY-Y(1,L))**2+(ZZZ-Z(1,L))**2)
 259 GGG = GAMB(LPS)*(SIG1+SIG2)/(SIG1*SIG2*((SIG1+SIG2)**2-1.)))
     U(I,J) = U(I,J) + XNU1 + GGG
     V(I,J) = V(I,J) + XNU2 + GGG
     W(I,J) = W(I,J) + XNU3 + GGG
```

```
GO TO 27
260 \text{ M(I,J)} = \text{M(I,J)}-\text{GAMB(LPS)}*FRB
  27 CONTINUE
     CALL FUSLGE(X(I,J),Y(I,J),Z(I,J),UF,VF,WF)
     U(I,J) = U(I,J) + XMCL + UF
     V(I,J) = V(I,J)+VF
     W(I,J) = W(I,J)-XMSL+WF
28 CONTINUE
  29 CONTINUE
     IF(NTAPE.EQ.O) GO TO 30
     WRITE(4)PSI,XMU,XLAM,ALPHAT,NB,NRW,NA,NW
     WRITE(4) ((X(I,J),Y(I,J),Z(I,J),U(I,J),V(I,J),W(I,J),GAMA(I,J),
               A(I,J),I=1,NW1),J=1,NB1)
30 IFINCT NE OIGO TO 31
      IF(NXPT.NE.O)CALL VLCTY
     CALL OUTPUT
  31 \text{ NCT} = \text{NCT+1}
     IF(NCT_*GE_*NPINT)NCT = 0
    \cdot PSI = PSI + DPSI
  NPS = NPS+1
      IF (NPS \cdot GT \cdot NA) NPS = 1
     IF(PSI.LE.PSIF) GO TO 32
      IF(NTAPE.NE.O) END FILE 4
      IF(NPNCH.EQ.O) GO TO 1
     PUNCH 1004
                   HELICOPTER WAKE VORTICITY CALCULATIONS - HARVEY
10C4 FORMAT (74HZZ
                       ZZ )
     ISELIB
     PUNCH 1001, ((A(I,J),I=1,NW),J=1,NB)
     PUNCH 1003, ((X(I,J), I=1, NW1), J=1, NB)
     PUNCH 1003, ((Y(I,J),I=1,NWI),J=1,NB)
      PUNCH 1003, ((Z(I,J), I=1,NW1), J=1,NB)
     <u>60 TO 1</u>
  32 DO 35 J=1,NB1
      TX1 = X(1,J)
      TY1 = Y(1,J)
      TZ1 = Z(1,3)
      DO 33 I=2,NW1
 TY2 = TY
      TZ2 = TZ1
      TX1 = X(I,J)
      TY1 = Y(I,J)
      TZ1 = Z(I,J)
      X(I,J) = TX2+XLAM+U(I-1,J)+DPSI
      Y(I,J) = TY2+XLAM*V(I-1,J)*DPSI
     Z(I,J) = TZ2+XLAM+W(I-1,J)+DPSI
   33 CONTINUE
      XJ = FLOAT(J-1)*TPNB
      X(1,J) = COS(PSI+XJ)
      \frac{Y(1,J)}{X+J} = \frac{Y(1,J)}{X+J}
      Z(1,J) = 0.0
  35 CONTINUE
      DO 38 J=1,NB1
     JPS = MOD(NPS+(NA*(J-1))/NB+NAB,NA)
      IF(JPS.EQ.O) JPS = NA
      JPS1 = JPS-1
```

```
IF(JPS1.EQ.O)JPSI = NA
                           SEG1 = SEG(1,J)
                           GAM1 = GAMA(1,J)
                  TA1 = A(1,J)
36 DO 37 1=2,NW
                           GAM2 = GAM1
                            GAM1 = GAMA(I,J)
                           GAMA(I,J) = GAM2
                           SEG2 = SEG1
                           SEG1 = SEG(I,J)
                           SEG(I,J) = SQRT((X(I,J)-X(I+1,J))**2+(Y(I,J)-Y(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J)-X(I+1,J))**2+(Z(I,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+1,J)-X(I+
                                                                                                                                 Z(I+1,J))**2)
                           TA2 = TA1
             \frac{TAl = A(I,J)}{A(I,J) = TA2*SQRT(SEG2/SEG(I,J))}
37 CONTINUE
                           SEG(1,J) = SQRT((X(1,J)-X(2,J))**2+(Y(1,J)-Y(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J))**2+(Z(1,J)-X(2,J)-X(2,J))**2+(Z(1,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(2,J)-X(
                                                                                                                                  Z(2,J))**2)
                           A(1,J) = Al(JPS)
                          GAMA(1,J) = (GAMB(JPS)+GAMB(JPS1))/2.0
38 CONTINUE
                           GO TO 13
                           END
```

```
$IBMAP ZZCLR
               REF
                            SUBROUTINE CLEAR
               SUBROUTINE TO SET FORTRAN LOGATIONS TO ZERO
               CALLING SEQUENCE - CALL CLEAR(X,Y)
       ENTRY
               CLEAR
       BCI
               1.CLEAR
CLEAR TRA
               ##
       SXA
               SVE,1
       SXA
               SVE+1,4
       LAC
               CLEAR, 4
       CLA
               3,4
       SUB
               2,4
 . ... PAX
               2.1
       IMI
               ORDR
                                  IN CASE LOC(Y) LESS THAN LOC(X)
       CLA
               3,4
       STA
               ZERO
       TRA
               ZERO
 ORDR CLA
               2,4
 ZERO STZ
               ZERO
               **,1
               ZERO,1,1
       XIT
       STZ+
               2.4
       STZ*
               3,4
       LXA
               SVE.1
       LXA
               SVE+1,4
CLEAR
       TRA*
  SVE BSS
               2
       END
```

\$IBFTC ZZIDI LIST,REF
C WAKE VORTICITY CALCULATION PROGRAM - SUBROUTINE IDOUT
SUBRUUTINE !DCUT
COMMEN X(340,4),Y(340,4),Z(340,4),U(340,4),V(340,4),W(340,4),
GAMA(345,4), SEG(345,4), GAMB1(100), A1(100), A(340,4), PI, RAD,
2 VMP, XMCL, XMSL, NB, NRW, NA, NW, NOPT, NTAPE, NPRINT, NDVCH, PSIG,
3 XMU, XLAM, ALPHAT, PINT, PSIF, XNA, DPSI, NB1, NW1, XNW, XNB, TPNB,
4 SAT, CAT, C1, C2, PS1, TP1, X1, T1, T2, XJ, NPS, JPS, IPS, IPS1, XXX, YYY,
5 ZZZ, IST, INC, IFLG, SIG1, SIG2, SIG3, GGG, DEN, XNU1, XNU2, XNU3, IR1,
6 XMX,XMY,XMZ,SIG4,SIG5,RK,SQI1,SF,SQI,SG,BF,LPS,SEG1,SEG2,
7 SUM, ENCT, XIPT(400), YIPT(400), ZIPT(400), VX(400), VY(40),
8 VZ(40)), VXF(400), VYF(400), VZF(400), NXPT, NAB, FACTR, RB
COMMUN /FUSE/ XBAR(100), YBAR(100), ZBAR(100), SIGX(100), SIGZ(100),
1 X11(10:),X12(100),X13(100),X14(100),ETA1(100),ETA2(100),
2 ETA3(100), ETA4(100), XLE(100), XME(100), XNE(100), XLZ(100),
3 $XXZ(100), XNZ(100), NFPI, RJ(4), EJ(4), HJ(4), EMJ(4), D1(100),$
4 D2(103),D3(103),D4(103),VXINF,VYINF,VZINF,UF,VF,WF
1 WRITE(6,10C3)NB,NRW,NA,NFPT,PSIC,PSIF,XLAM,XMU,ALPHAT,RB,FACTR
1000 FCKMAT(1H1,49x33HHELICOPTER WAKE VORTICITY PROGRAM //45x31HNUMBER
10F BLADES = I11 /45x31HNUMBER UF REVOLUTIONS OF WAKE =
2 III /45x31HNUMBER CF AZIMUTH STATIONS =III/45x31HNUMBER OF FUS
XELAGE PCINTS = 111/45X23HPSI (INITIAL) =
3 F11.3,8H CEGREES /45x23HPSI (FINAL) =F11.3,
4 8H DEGREES /45X23HLAMBDA =E12.5 /45X23HMU
5 =E12.5 /45X23HALPHAT =F11.3.8H DEGREES /
6 45x23HR/B =F11.3/45X23HVZ INFINITY FACTO
7R = F11.3
2 DPS = 360.c/FLOAT(NA)
The state of the s
PS = 0.:
WRITE(6,10C1)
WRITE(6,1001) 1001 FORMAT(//30X3HPSI,15X22H STRENGTH OF BLADE 1 ,14X20HCORE SIZE AT
WRITE(6,1001)  1001 FORMAT(//30X3HPSI,15X22H STRENGTH OF BLADE 1 ,14X20HCORE SIZE AT 1BLADE 1 )
WRITE(6,10C1)  1001 FORMAT(//3CX3HPSI,15X22H STRENGTH OF BLADE 1 ,14X20HCORE SIZE AT 1BLADE 1 )  3 DG 4 I=1,NA
WRITE(6,10C1)  1001 FORMAT(//3CX3HPSI,15X22H STRENGTH OF BLADE 1 ,14X20HCURE SIZE AT 1BLADE 1 )  3 DG 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)
WRITE(6,10C1)  1001 FORMAT(//3CX3HPSI,15X22H STRENGTH OF BLADE 1 ,14X20HCORE SIZE AT  1BLADE 1 )  3 DC 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E30.5,E35.5)
WRITE(6,10C1)  1001 FORMAT(//3CX3HPSI,15X22H STRENGTH OF BLADE 1 ,14X20HCORE SIZE AT  1BLADE 1 )  3 DC 4 I=1,NA  WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E36.5,E35.5) PS = PS+DPS
WRITE(6,10C1)  10C1 FORMAT(//3CX3HPSI,15X22H STRENGTH OF BLADE 1 ,14X20HCORE SIZE AT 1BLADE 1 )  3 DC 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5) PS = PS+DPS 4 CONTINUE
WRITE(6,10C1)  1UG1 FORMAT(//3CX3HPSI,15X22H STRENGTH UF BLADE 1 ,14X20HCURE SIZE AT 1BLADE 1 )  3 DC 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5)  PS = PS+DPS  4 CUNTINUE RETURN
WRITE(6,10C1)  10C1 FORMAT(//3CX3HPSI,15X22H STRENGTH OF BLADE 1 ,14X20HCORE SIZE AT 1BLADE 1 )  3 DC 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5) PS = PS+DPS 4 CONTINUE
WRITE(6,10C1)  1UG1 FORMAT(//3CX3HPSI,15X22H STRENGTH UF BLADE 1 ,14X20HCURE SIZE AT 1BLADE 1 )  3 DC 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5)  PS = PS+DPS  4 CUNTINUE RETURN
WRITE(6,10C1)  1UG1 FORMAT(//3CX3HPSI,15X22H STRENGTH UF BLADE 1 ,14X20HCURE SIZE AT 1BLADE 1 )  3 UG 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5)  PS = PS+DPS  4 CUNTINUE RETURN
WRITE(6,10C1)  1UG1 FORMAT(//3CX3HPSI,15X22H STRENGTH UF BLADE 1 ,14X20HCURE SIZE AT 1BLADE 1 )  3 UG 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5)  PS = PS+DPS  4 CUNTINUE RETURN
WRITE(6,10C1)  1UG1 FORMAT(//3CX3HPSI,15X22H STRENGTH UF BLADE 1 ,14X20HCURE SIZE AT 1BLADE 1 )  3 UG 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5)  PS = PS+DPS  4 CUNTINUE RETURN
WRITE(6,10C1)  1UG1 FORMAT(//3CX3HPSI,15X22H STRENGTH UF BLADE 1 ,14X20HCURE SIZE AT 1BLADE 1 )  3 UG 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5)  PS = PS+DPS  4 CUNTINUE RETURN
WRITE(6,10C1)  1UG1 FORMAT(//3CX3HPSI,15X22H STRENGTH UF BLADE 1 ,14X20HCURE SIZE AT 1BLADE 1 )  3 UG 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5)  PS = PS+DPS  4 CUNTINUE RETURN
WRITE(6,10C1)  1UG1 FORMAT(//3CX3HPSI,15X22H STRENGTH UF BLADE 1 ,14X20HCURE SIZE AT 1BLADE 1 )  3 UG 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5)  PS = PS+DPS  4 CUNTINUE RETURN
WRITE(6,10C1)  1UG1 FORMAT(//3CX3HPSI,15X22H STRENGTH UF BLADE 1 ,14X20HCURE SIZE AT 1BLADE 1 )  3 UG 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5)  PS = PS+DPS  4 CUNTINUE RETURN
WRITE(6,10C1)  1UG1 FORMAT(//3CX3HPSI,15X22H STRENGTH UF BLADE 1 ,14X20HCURE SIZE AT 1BLADE 1 )  3 UG 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5)  PS = PS+DPS  4 CUNTINUE RETURN
WRITE(6,10C1)  1UG1 FORMAT(//3CX3HPSI,15X22H STRENGTH UF BLADE 1 ,14X20HCURE SIZE AT 1BLADE 1 )  3 UG 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5)  PS = PS+DPS  4 CUNTINUE RETURN
WRITE(6,10C1)  1UG1 FORMAT(//3CX3HPSI,15X22H STRENGTH UF BLADE 1 ,14X20HCURE SIZE AT 1BLADE 1 )  3 UG 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5)  PS = PS+DPS  4 CUNTINUE RETURN
WRITE(6,10C1)  1UG1 FORMAT(//3CX3HPSI,15X22H STRENGTH UF BLADE 1 ,14X20HCURE SIZE AT 1BLADE 1 )  3 DC 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5)  PS = PS+DPS  4 CUNTINUE RETURN
WRITE(6,10C1)  1UG1 FORMAT(//3CX3HPSI,15X22H STRENGTH UF BLADE 1 ,14X20HCURE SIZE AT 1BLADE 1 )  3 DC 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5)  PS = PS+DPS  4 CUNTINUE RETURN
WRITE(6,10C1)  1UG1 FORMAT(//3CX3HPSI,15X22H STRENGTH UF BLADE 1 ,14X20HCURE SIZE AT 1BLADE 1 )  3 DC 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5)  PS = PS+DPS  4 CUNTINUE RETURN
WRITE(6,10C1)  1UG1 FORMAT(//3CX3HPSI,15X22H STRENGTH UF BLADE 1 ,14X20HCURE SIZE AT 1BLADE 1 )  3 DC 4 I=1,NA WRITE(6,10C2)PS,GAMB1(I),A1(I)  1002 FORMAT(F35.3,E3C.5,E35.5)  PS = PS+DPS  4 CUNTINUE RETURN

\$1BFTC	ZZOUTP	Ll	ST-,R	£F														
C W	AKE VO	RTIC	ITY	CAL	CULA	TICN	PR	OGRA	4M -	·S	UBR	UUT	INE	ΩU	TPU	T		
S	UBROUT	INE	CUTP	UT														
С	OMMON	X ( 3 4	0.4)	.Y1	340.	4).7	134	0.4	) . U (	34	0.4	) . V	(34	0.4	) . W	(340	.4).	
1																	PI,RAD,	
2																	,PSIO,	
3																	TPNB,	
4																	,XXX,YY	٧.
<del></del> 5																	XNU3, IR	
6																	1,SEG2,	. ,
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8						-												
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1	•	_				),A(						-		•	-	•		
1003 F	ORMAT (	4X5	HSTA	Τ.,	1CX1	HX,1	4 X 1	HY.	4X1	HZ	.14	X2H	VX.	1 3 X	2HV	Y.13	X2HVZ.	
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1		1 4 Y 2	NZ 01.	131	2HVY	,13X	2HV	7 //	. N . F	בט	. RE'	15 (	 	1	<b>9</b> 1 T	VIIII	0 1 7 V E(1 C )	
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```
SIBFTC ZZFSLG LIST, REF
      WAKE VORTICITY CALCULATION PROGRAM - SUBROUTINE FUSLGE
      SUBROUTINE FUSLGE(XC, YC, ZD, UFD, VFD, WFD)
      COMMUN /FUSE/ XBAR(100), YBAR(10C), ZBAR(100), SIGX(100), SIGZ(100),
              XII(100), XI2(100), XI3(100), XI4(100), ETA1(100), ETA2(100),
     2
              ETA3(100), ETA4(100), XLE(100), XME(100), XNE(100), XLZ(100),
              XMZ(100),XNZ(100),NFPT,RJ(4),EJ(4),HJ(4),EMJ(4),D1(100),
     3
              D2(100), D3(100), D4(10C), VXINF, VYINF, VZINF, UF, VF, WF
      DIMENSICN XIK(100,4), ETAK(100,4), DDJ(100,4)
      EQUIVALENCE (XIK, XII), (ETAK, ETAI), (DDJ, D1)
    1 SUMU = C.0
      SUMV = 0.0
      SUMW = G.O
      IF(NFPT.EQ.O) GO TO 13
             J=1,NFPT
    2 DO 12
      NFLG = 1
      XLX = XME(J)*XNZ(J)-XMZ(J)*XNE(J)
      XMX = XNE(J)*XLZ(J)-XNZ(J)*XLE(J)
      XNX = XLE(J)*XMZ(J)-XLZ(J)*XME(J)
      XB = XD - XBAR(J)
      YB = YD - YBAR(J)
      ZB = ZD-ZBAR(J)
      D5 = (XI3(J)-XI1(J))**2+(ETA3(J)-ETA1(J))**2
      D6 = (XI4(J)-XI2(J))**2+(ETA4(J)-ETA2(J))**2
      D7 = AMAX1(D5,D6)
    3 XI = XLX*XB+XMX*YB+XNX*ZB
      ETA = XLE(J)*XB+XME(J)*YB+XNE(J)*ZB
      ZETA = XLZ(J)*XB+XMZ(J)*YB+XNZ(J)*ZB
      RO = XI**2+ETA**2+ZETA**2
      TJ = R0/D7
      IF(TJ.LT.6.0) GO TO 5
    4 SJ = .5*(XI3(J)-XI1(J))*(ETA2(J)-ETA4(J))/(RO*SGRT(RO))
      VXI = SJ*XI
      VETA = SJ*ETA
      VZETA = SJ*ZETA
      GD TU 90
    5 DO 6 I=1,4
      RJ(I) = SQRT((XI-XIK(J,I))**2*(ETA-ETAK(J,I))**2*ZETA**2)
      EJ(I) = ZETA**2+(XI-XIK(J,I))**2
      HJ(I) = (EIA-ETAK(J,I))*(XI-XIK(J,I))
      I1 = I+1
       IF(I \cdot EQ \cdot 4) II = 1
      TRM1 = XIK(J,I1) - XIK(J,I)
       IF(TRM1.EQ.C.C) TRM1 = 1.0E-6
      EMJ(I) = (ETAK(J,I1)-ETAK(J,I))/TRM1
     6 CONTINUE
      0.0 = IXV
      VETA = 0.0
      VZETA = 0.C
    7 DU 9 I=1,4
      I1 = I+1
       IF(I.EQ.4) I1 = 1
      TRM1 = (RJ(I)+RJ(II)-CDJ(J,I))/(RJ(I)+RJ(II)+DDJ(J,I))
       TRM1 = ALGG(TRM1)
       TRM2 = (ETAK(J,II) - ETAK(J,I)) / CCJ(J,I)
       TRM3 = (XIK(J,I)-XIK(J,II))/CDJ(J,I)
```

AXI = AXI + IKW5 * IKW1
VETA = VETA+TRM3*TRM1
8 IF(ZETA.EQ.O.C) GO TO 9
TRM4 = ATAN((EMJ(I)*EJ(I)-HJ(I))/(ZETA*RJ(I)))
TRM5 = ATAN((EMJ(I)*EJ(II)-HJ(II))/(ZETA*RJ(II)))
VZETA = VZETA+TRM4-TRM5
9 CONTINUE
90 VVX = XLX*VXI+XLE(J)*VETA+XLZ(J)*VZETA
VVY = XMX*VXI+XME(J)*VETA+XMZ(J)*VZETA
VVZ = XNX*VXI+XNE(J)*VETA+XNZ(J)*VZETA
GO TU (ÎÙ,11),NFLG
$\frac{10 \text{ VVVX} = \text{VVX}}{10 \text{ VVX}} = \frac{10 \text{ VVX}}{10 \text{ VVX}} = \frac{10 \text{ VVX}}{10 \text{ VX}} = \frac{10 \text{ VX}}{10 \text{ VX}} $
$\nabla \nabla \nabla Y = \nabla \nabla Y$
VVVZ = VVZ
YB = -YD - YBAR(J)
NFLG = 2
GO TO 3
11 TRM = SIGX(J)*VXINF+SIGZ(J)*VZINF
SUMU = SUML+TRM* (VVVX+VVX)
SUMV = SUMV + IRM * (VVVY - VVY)
SUMW = SUMM+TRM*(VVVZ+VVZ)
12 CONTINUE
13 UFD = SUMU
VFD = SUMV
WFD = SUMW
RETURN
END
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•

```
SIBFTC ZZVLCT LIST, REF
             WAKE VORTICITY CALCULATION PROGRAM - SUBROUTINE VLCTY
             SUBRUUTINE VLCTY
             COMMON X(340,4),Y(340,4),Z(340,4),U(340,4),V(340,4),W(340,4),
                         GAMA(34C,4),SEG(345,4),GAMB1(100),A1(100),A(34C,4),PI,RAD,
          1
                           VMP, XMCL, XMSL, NB, NRW, NA, NW, NGPT, NTAPE, NPRINT, NDVCH, PSIC,
          2
                           XMU, XLAM, ALPHAT, PINT, PSIF, XNA, DPSI, NB1, Nk1, XNW, XNB, TPNB,
          3
                           SAT, CAT, C1, C2, PSI, TPI, X1, T1, T2, XJ, NPS, JPS, IPS, IPS1, XXX, YYY,
                           ZZZ, IST, IND, IFLG, SIG1, SIG2, SIG3, GGG, DEN, XNU1, XNU2, XNU3, IR1,
          5
                           XMX, XMY, XMZ, SIG4, SIG5, RK, SQI1, SF, SQI, SG, BF, LPS, SEG1, SEG2,
          6
                           SUM, LNCT, XIPT (400), YIPT (400), ZIPT (400), VX(400), VY(400),
                           VZ(403), VXF(400), VYF(400), VZF(403), NXPT, NAB, FACTR, RB
         1 DC 7 I=1.NXPT
             YX(I) = 0.0
             VY(I) = C \cdot C
             VZ(I) = 0.0
         2 D0 5 J=1.81
             Z(1,J))**2)
         3 00 4
                       K=1, NW
             SIG1 = SIG2
             2(K+1,J))**2)
             SEGSQ = SEG(K,J)**2
             HM1 = SIG1**2+SIG2**2
             IF(HM1.GT.SEGSQ)GO TC 30
             HM2 = .25*((SIG1+SIG2)**2-SEGSL)*(SEGSC-(SIG1-SIG2)**2)/SEGSC
             IF(HM2.GT.A(K,J)**2)GC TO 3C
             GGG = GAMA(K,J)/SEG(K,J)
       \frac{GO\ TU\ 31}{30\ GGG} = \frac{GAMA(K,J)*(SIG1+SIG2)/(SIG1*SIG2*((SIG1+SIG2)**2-SEGSQ))}{GGG} = \frac{GAMA(K,J)*(SIG1+SIG2)/(SIG1*SIG2*((SIG1+SIG2)**2-SEGSQ))}{GGG} = \frac{GAMA(K,J)*(SIG1+SIG2)/(SIG1*SIG2*((SIG1+SIG2)**2-SEGSQ))}{GGG} = \frac{GAMA(K,J)*(SIG1+SIG2)/(SIG1*SIG2*((SIG1+SIG2)**2-SEGSQ))}{GGG} = \frac{GAMA(K,J)*(SIG1+SIG2)/(SIG1*SIG2*((SIG1+SIG2)**2-SEGSQ))}{GGG} = \frac{GAMA(K,J)*(SIG1+SIG2)/(SIG1*SIG2*((SIG1+SIG2)**2-SEGSQ))}{GGG} = \frac{GAMA(K,J)*(SIG1+SIG2)/(SIG1**SIG2*((SIG1+SIG2)**2-SEGSQ))}{GGG} = \frac{GAMA(K,J)*(SIG1+SIG2)/(SIG1**SIG2*((SIG1+SIG2)**2-SEGSQ))}{GGG} = \frac{GAMA(K,J)*(SIG1+SIG2)/(SIG1**SIG2*((SIG1+SIG2)**2-SEGSQ))}{GGG} = \frac{GAMA(K,J)*(SIG1+SIG2)/(SIG1**SIG2*((SIG1+SIG2)**2-SEGSQ))}{GGG} = \frac{GAMA(K,J)*(SIG1+SIG2)/(SIG1**SIG2*((SIG1+SIG2)**2-SEGSQ))}{GGG} = \frac{GAMA(K,J)*(SIG1**SIG2*((SIG1**SIG2)**2-SEGSQ))}{GGG} = \frac{GAMA(K,J)*(SIG1**SIG2*((SIG1**SIG2)**2-SEGSQ))}{GGG} = \frac{GAMA(K,J)*(SIG1**SIG2*((SIG1**SIG2)**2-SEGSQ)}{GGG} = \frac{GAMA(K,J)*(SIG1**SIG2*((SIG1**SIG2)**2-SEGSQ)}{GGG} = \frac{GAMA(K,J)*(SIG1**SIG2*((SIG1**SIG2)**2-SEGSQ)}{GGG} = \frac{GAMA(K,J)*(SIG1**SIG2*((SIG1**SIG2)**3-SEGSQ)}{GGG} = \frac{GAMA(K,J)*(SIG1**SIG3*((SIG1**SIG3)**3-SEGSQ)}{GGG} = \frac{GAMA(K,J)*(SIG1**SIG3*((SIG1**SIG3)**3-SE
       31 XNU1 = (YIPT(I)-Y(K,J))*(Z(K,J)-Z(K+1,J))-(ZIPT(I)-Z(K,J))*
                             (Y(K,J)-Y(K+1,J))
             XNU2 = (ZIPT(I)-Z(K,J))*(X(K,J)-X(K+1,J))-(XIPT(I)-X(K,J))*
                             (Z(K,J)-Z(K+1,J))
             XNU3 = (XIPT(I)-X(K,J))*(Y(K,J)-Y(K+1,J))-(YIPT(I)-Y(K,J))*
                             (X(K,J)-X(K+1,J))
             VX(I) = VX(I) + XNU1 + GGG
             VY(I) = VY(I)+XNU2*GGG
             VZ(I) = VZ(I) + XNU3 * GGG
          4 CONTINUE
          5 CONTINUE
              SIGI = SQRT(XIP\Gamma(I) **2 + YIPT(I) **2 + ZIPT/I) **2)
             DO 6 L=1,NB
             LPS = MCD(NPS+(NA*(L-1))/NB+NAB,NA)
              IF(LPS \cdot EQ \cdot C) LPS = NA
             XNU1 = -YIPT(I)*Z(1,L)+ZIPT(I)*Y(1,L)
              XNU2 = -ZIPT(I)*X(1,L)*XIPT(I)*Z(1,L)
             XNU3 = -XIPT(I)*Y(I,L)+YIPT(I)*X(I,L)
              Z(1,L))**2)
              DEN = SIG1*SIG2*((SIG1+SIG2)**2-1.0)
              IF(DEN.EQ.O.O) DEN = .001
              GGG = GAMB1(LPS)*(SIG1+SIG2)/DEN
              VX(I) = VX(I) + XNU1 + GGG
              VY(I) = VY(I) + XNU2 + GGG
```

VZ(I) = VZ(I)+XNU3+GGG 6 CCNTINUE
VX(I) = VX(I)+XMCL+VXF(I) VY(I) = VY(I)+VYF(I)
$\frac{VZ(1) = VZ(1) - XMSL + VZF(1)}{7 \text{ CONTINUE}}$
RETURN END
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### APPENDIX II

# OPERATIONAL INFORMATION FOR THE SUPPLEMENTAL FUSELAGE PROGRAM

This program is written completely in FORTRAN IV.

# INPUTS

CARD 1 NPTS: Number of fuselage elements  $N_{\varphi}$ 

NPRNT: Number of  $B_{ij}$  coefficients to be printed;

i.e., NPRNT = (NPTS)(NPTS).

EPS: Desired accuracy in iterative solution

of equations; i.e., if EPS = .001, the

solution will be obtained to within + 0.1%

of the exact result.

NIT: Maximum number of iterations to be

allowed in solving the equations (in case

of divergence of the iterations).

NDUCH: Not used.

CARD 2, 3, ..., (2)(NPTS) + 1  $x_{11}$ ,  $y_{11}$ ,  $y_{11}$ ;  $x_{21}$ ,  $y_{21}$ ,  $y_{21}$ .

x31. 431, 331; x41. 441. 341.

x12. 412, 312; x22, 422, 322.

etc.

A listing of the program is given on the pages which follow.

```
$IBFTC ZZHFPF LIST, REF
       CATCULATION OF POTENTIAL FLOW ABOUT A HELICOPTER FUSELAGE
С
       CCMMGN X1(101), X2(100), X3(100), X4(100), Y1(100), Y2(100), Y3(100),
               Y4(100),21(100),22(100),23(100),24(100),XBAR(100),YBAR(100)
               , ZEAR (10L), AMIX (3,4), XPI (4), YPT (4), ZPT (4), XII (10~), XI2(100)
      2
               x13(100),x14(103),E1A1(100),ETA2(100),ETA3(100),ETA4(100),
               ZETA1(10:),ZETA2(10:),ZETA3(100),ZETA4(10:),XLX(10:),
      4
               XMX(ICC), XNX(ICC), XLE(ICC), XME(ICC), XNE(IGC), XLZ(ICO),
               XMZ(13C), XNZ(1CC), RIJ(4), EIJ(4), HIJ(4), D1(1CC), D2(100),
      6
               E3(10C),C4(1CC),B(1CC,1C2),SIGX(1CC),SIGZ(1CC),NPTS,NCVCH,
               EPS, AN, BN, GN, AX, BX, GX, AE, BE, GE, CX, CE, CZ, C5, D6, D7, SJ, NFLG,
      8
               EM1.EM2.EM3.EM4.XPF,YPP.ZPP,YRPP.XIIJ,ETAIJ.ZETA[J.RC.R]
       CCMMCN XIRIJ,ETARIJ,ZETRIJ,TIJ,TRIJ,VXI,VETA,VZETA,TMP1,TMP2,TMP3,
               TMP4, TMP, VX, VY, VZ, AIJ, ARIJ, N1, N2, APRAT, MPRAT, NIT
       DIMENSICH X(103,4),Y(180,4),Z(100,4),XIK(180,4),ETAK(100,4),
                  ZETAK(10C,4)
       EQUIVALENCE (X:X1), (Y,Y1), (Z,Z1), (XIK,XI1), (ETAK, ETA1), (ZETAK,
                     ZETALI
     1 READ 1GCC, NPTS, NPRNT, EPS, NIT, NEVCH
 1000 FCRMAT(216, F6.0, 216)
       READ 1001, ((X(I,J),Y(I,J),Z(I,J),J=1,4),I=1,NPTS)
 1001 FCRMAT(6F12.5)
2 DC 18 I=1,NPIS
       \frac{\Delta N}{BN} = \frac{(Y4(1)-Y2(1))*(Z3(1)-Z1(1))-(Z4(1)-Z2(1))*(Y3(1)-Y1(1))}{BN} = \frac{(Z4(1)-Z2(1))*(X3(1)-Z1(1))-(X4(1)-X2(1))*(Z3(1)-Z1(1))}{(Z3(1)-Z1(1))}
       GN = (X4(1)-X2(1))*(Y3(1)-Y1(1))-(Y4(1)-Y2(1))*(X3(1)-X1(1))
       XEAR(I) = (XI(I)+X2(I)+X3(I)+X4(I))/4.C
      YBAR(I) = (Y1(I)+Y2(I)+Y3(I)+Y4(I))/4.C
        ZEAR(I) = (21(I)+22(I)+23(I)+24(I))/4...
    3 IF(AN.NE.C.C) GC TC 8
       IF(BN.NE.C.J) GC TC 8
       IF (GN.NE.C.T) GC TC 6
     4 WRITE(6,1CC2)I,(X(I,J),Y(I,J),Z(I,J),J=1,4)
  1062 FCRMAT(4CH BAC SET UF PCINIS FUR GUADRILATERAL NO. 15/4(3F9.4,5X))
       GC TC 1
     6 DC 7 J=1,4
       XPI(J) = X(I,J)-XBAR(I)
       YPT(J) = Y(I,J) - YEAR(I)
       ZPI(J) = C.C
     7 CCNTINUE
       GC TL 14
     AMIX(1,1) = AN
       AMIX(1,2) = BN
       AMIX(1,3) = GA
       AMIX(2,1) = 8N
       ANTX (2, 2) = - AN
       AMIX(2;3) = 0.0
       IF(AN.NE.C.) CC TC 11
     9 \text{ AM}(3,1) = 0.3
       AMIX(3,2) = GN
       AMIX(3,3) = -BN
       DC 1 J=1,4
       AMIX(1,4) = BA*YBAR(I)+GA*ZBAR(I)
       AMIX(2,4) = BN*X(I,J)
       AMTX(3,4) = GN*Y(I,J)-BN*Z(I,J)
       CALL SIMSCL (AMIX, 3, 3)
```

```
XPT(J) = APIX(1,4)-XEAR(I)
   YPI(J) = AMIX(2,4)-YUAR(I)
    ZPI(J) = AMIX(3,4)-ZPAR(I)
IC CENTINUE
   GC TL 14
11 \text{ AMIX}(3,1) = GN
    AMTX(3,2) = C.0
   AMIX(3,3) = -AN
12 DC 13 J=1,4
   \underline{AMTX(1,4)} = AN * XRAR(I) + BN * YEAR(I) + GN * ZBAR(I)
   AMTX(2,4) = BN*X(I,J)-AN*Y(I,J)
    \underline{AMTX(3,4)} = \underline{GN*X(1,J)} - AN*Z(1,J)
   CALL SIMSCL(AMTX, 3, 3)
   XPT(J) = AFTX(1,4)-XEAR(I)
   YPT(J) = AMTX(2,-1)-YBAR(I)
   \frac{ZPT(J) = AMTX(3,4) - ZPAR(I)}{}
13 CENTINUE
14 AX = XPT(3) - XFI(1)
    BX = YPT(3) - YFT(1)
   GX = ZPT(3) - ZPT(1)
   AE = BN*GX-BX*GN
   BE = GN + AX - GX + AN
    GE = AN*EX-AX*EN
   CX = 1 \cdot G/SCRT(AX##2+BX##2+GX##2)
    CE = 1 \cdot G/SCRT(AE**2+BE**2+GE**2)
    CZ = 1 \cdot C/SCRT(\Delta N ** 2 + BN ** 2 + GN ** 2)
    XLX(1) = CX*AX
   XMX(I) = CX#EX
    XhX(I) = Cx*Gx
   XLE(I) = CE *AE
    XME(1) = CE*BE
   XNE(I) = CE*GE
    XLZ(I) = CZ#AN
    XYZ(I) = CZ*BN
    XNZ(I) = CZ*GN
 16 DC 17 J=1.4
    XIK(I,J) = XLX(I) *XPT(J) + XMX(I) *YPT(J) + XAX(I) *ZPT(J)
    ETAK(I_*J) = XLE(I)*XPT(J)*XPE(I)*YPT(J)*XNE(I)*ZPT(J)
    ZETAK(I,J) = XLZ(I)*XPT(J)+XPZ(I)*YPT(J)+XNZ(I)*ZPT(J)
 17 CCNTINUE
 18 CCNTINUE
 19 DC 31 J=1, NPTS
    D1(J) = SCRY((XI2(J)-XI1(J))**2+(ETA2(J)-ETA1(J))**2)
    D2(J) = SCRT((X13(J)-X12(J))+2+(ETA3(J)-ETA2(J))+2)
    D3(J) = SCRT((XI4(J)-XI3(J))**2+(ETA4(J)-ETA3(J))**2)
    D4(J) = SCRT((XII(J)-XI4(J))**2+(ETAI(J)-ETA4(J))**2)
^{\circ}. D5 = (XI3(J)-XI1(J))**2+(ETA3(J)-ETA1(J))**2
    D6 = (XI4(J)-XI2(J))**2+(ETA4(J)-ETA2(J))**2
    D7 = AMAXI(C5,D6)
    SJ = .5*(XI3(J)-XI1(J))*(ETA2(J)-ETA4(J))
    TRF = XI2(J) - XI1(J)
    IF(TRM.EC.C.C) IRM = 1.CE-6
    EM1 = (ETA2(J)-ETA1(J))/TRM
    IRM' = XI3(J) - XI2(J)
    IF(TRM.EC.C.O)TRM = 1.0E-6
    EM2 = (ETA3(J)-ETA2(J))/TRM
```

```
TRM = XI4(J)-XI3(J)
     IF(TRM.EQ.C.O)TRM = 1.CE-6
     EM3 = (ETA4(J)-ETA3(J))/TRM
     TRM = XII(J) - XI4(J)
      IF(TRM.EC.C.O)TRM = 1.CE-6
      EM4 = (ETA1(J)-ETA4(J))/TRM
20 DC 3C I=1, NPTS
     NFLG = 1
     XPP = XEAR(I) - XEAR(J)
      YPP = YEAR(I) - YEAR(J)
      ZPP = ZEAR(I) - ZBAR(J)
      YRPP = -YBAR(I) - YEAR(J)
      XIIJ = XLX(J)*XPP+XPX(J)*YPP+XAX(J)*ZPP
      ETAIJ = XLE(J) + XPP+XME(J) + YPF+XNE(J) + ZPP
      ZETAIJ = XLZ(J) *XPP+XMZ(J) *YFP+XMZ(J) *ZPF
      XIRIJ = XLX(J)*XPP+XYX(J)*YRPP+XXX(J)*ZPP
      ETARIJ = XLE(J) * XPP+XME(J) * YRPP+XNE(J) * ZPP
      ZETRIJ = XLZ(J) * XPP + XMZ(J) * YRPF + XMZ(J) * ZFP
      R1 = XIRIJ**2+ETARIJ**2+ZETRIJ*42
      RC = XIIJ**2+ETAIJ**2+ZETAIJ**2
      TIJ = RG/C7
      TRIJ = R1/C7
21 IF(I.NE.J) GC TC 22
      VXI = G.C
       VETA = C.C
      <u>YZETA = 6.2831853C72</u>
GC TL 27
22 IF(T1J.GT.6.C) GC TC 26
23 DC 24 K=1,4
      RIJ(K) = SCRT((XIIJ-XIK(J,K))**2+(ETAIJ-ETAK(J,K))**2+ZETAIJ**2)
       EIJ\{K\} = ZETAIJ**2+(XIIJ-XIK(J*K))**2
       HIJ(K) = (ETAIJ-ETAK(J,K))*(XIIJ-XIK(J,K))
24 CCNTINUE
      TMP1 = ALCG((RIJ(1)+RIJ(2)-C1(J))/(RIJ(1)+RIJ(2)+C1(J)))/C1(J)
       TMP2 = ALCG((RIJ(2)+RIJ(3)-C2(J))/(RIJ(2)+RIJ(3)+C2(J)))/C2(J)
       \frac{\text{TMP3} = ALCG((RIJ(3)+RIJ(4)-C3(J))/(RIJ(3)+RIJ(4)+C3(J)))/C3(J)}{\text{TMP3} = ALCG((RIJ(3)+RIJ(4)+C3(J)))/C3(J)}
       TMP4 = \Delta LCG((R[J(4)+RIJ(1)-C4(J)))/(RIJ(4)+RIJ(1)+C4(J)))/C4(J)
      VXI = (ETAI(J)-ETA2(J))*IMP1+(EIA2(J)-ETA3(J))*IMP2+(ETA3(J)-ETA3(J))*IMP2+(ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-ETA3(J)-
                     ETA4(J)) *TMP2+(ETA4(J)-ETA1(J)) *TMP4
       VXI
              = -vxI
       VETA = (XI1(J)-XI2(J))*TMP1+(XI2(J)-XI3(J))*TMP2+(XI3(J)-XI4(J))*
                        INF3+(XI4(J)-XI1(J))*TMF4____
       IF(ZETAIJ.NE.C..) GC TC 25
       VZEIA = C.C
GC TL 27
 25 \text{ VZETA} = \text{ATAN}((EM1*EIJ(1)-HIJ(1))/(ZETAIJ*RIJ(1)))-ATAN((EM1*EIJ(2))
                        *RIJ(2)))-ATAN((EM2*EIJ(3)-HIJ(3))/(ZETALJ*RIJ(3)))+
                        ATAN((EM3*EIJ(3)-HIJ(3))/(EN3*EIJ(3)))-ATAN((EM3*EIJ(4)
                        *RIJ(4)))-ATAN((EM4*ElJ(1)-HIJ(1))/(ZETAIJ*RIJ(1)))
       <u>GC_TL_27</u>
 26 TMP = SJ/(RC*SGRT(RL))
       VXI = XIIJ#TMP
       VEIA = ETAIJ*TMP
       VZETA = ZETAIJ*IMP
```

27 VX = XLX(J)*VXI+XLE(J)*VETA+XLZ(J)*VZETA
VY = XVX(J)*VXI+XVE(J)*VETA+XVZ(J)*VZETA
VZ = XNX(J)*VXI+XNE(J)*VETA+XNZ(J)*VZCTA
GC IL (28,29),NFLG
28  AIJ = XLZ(I)*VX+XYZ(I)*VY+XNZ(I)*VZ
<u>NFLG = 2</u>
XIIJ = XIRIJ
ETALJ = ETARLJ
ZETAIJ = ZETRIJ
RC = R1
TIJ = TRIJ
GC_IU_22
29 ARIJ = XLZ(I) #VX-XMZ(I) #VY+XNZ(I) #VZ
$B(I \cdot J) = AIJ + ARIJ$
30 CLATINUE
31 CCNTINUE
N1 = NPTS+1
N2 = NPTS+2
32 DC 33 I=1, NPTS
B(1,N1) = -XLZ(1)
B(1,N2) = -xN2(1)
33 CCNTINUE
IF(NPRNT.EC.3) GC TC 38
<u>MPRINT = MINC(NPRAT, AFTS)</u>
34 DC 37 I=1, MPRINT, 8
I8 = MINC(I+7, MPRINT)
WRITE(6,1CC3)I,18,MFRINT
1003 FCRMAT(1H1,44x42HPCTENTIAL FLCW ABOUT A HELICOPTER FUSELAGE //56x
1 1) LCT ( C(D   #12 2L = 12 CL   T = 1=12/)
1 11+EIJ FOR J =13,2+ -13,9+ , I = 1-13/)
35 DC 36 J=1.MPRINT
35 DC 36 J=1, MPRINT. WRITE(6,1CC4)(B(J,K),K=1,18)
35 DC 36 J=1,MPRINT. WRITE(6,1CC4)(B(J,K),K=1,18) 1CG4 FCRMAT(8E16.5)
35 DC 36 J=1, MPRINT. WRITE(6,1CC4)(B(J,K),K=1,18)
35 DC 36 J=1,MPRINT WRITE(6,1CC4)(B(J,K),K=1,18) 1CG4 FCRMAT(8E16.5) 36 CCNTINUE
35 DC 36 J=1,MPRINT WRITE(6,1CC4)(B(J,K),K=1,18) 1CG4 FCRMAT(8E16.5) 36 CCNTINUE 37 CCNTINUE
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC
35 DC 36 J=1, MPRINT WRITE(6,1CC4)(B(J,K),K=1,18) 1CC4 FCRMAT(8E16.5) 36 CCNTINUE 37 CCNTINUE 38 CALL SIMEC CALL CUTPLI
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1
35 DC 36 J=1, MPRINT WRITE(6,1CC4)(B(J,K),K=1,18) 1CC4 FCRMAT(8E16.5) 36 CCNTINUE 37 CCNTINUE 38 CALL SIMEC CALL CUTPLI
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1
35 DC 36 J=1, MPRINT  WRITE(6,1CC4)(B(J,K),K=1,18)  1CG4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1
35 DC 36 J=1,MPRINT  WRITE(6,1CC4)(B(J,K),K=I,I8)  1CC4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1  ENC
35 DC 36 J=1,MPRINT  WRITE(6,1CC4)(B(J,K),K=I,I8)  1CC4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1  ENC
35 DC 36 J=1,MPRINT  WRITE(6,1CC4)(B(J,K),K=I,I8)  1CC4 FCRMAT(8E16.5)  36 CCNTINUE  37 CCNTINUE  38 CALL SIMEC  CALL CUTPLI  GC TC 1  ENC

```
$18FTC ZZSMEG LIST, REF
      CALCULATION OF POTENTIAL FLOW ABOUT A HELICOPTER FUSELAGE - SIMEC
      SUBROUTINE SIMEQ
      <u>, 43(100), 42(100), 43(100), 44(100), 41(100), 42(100), 43(100)</u>
              Y4(10C), Z1(1CC), Z2(1CC), Z3(1CC), Z4(100), XBAR(10C), YBAR(1CC)
              *ZBAR(100), AMIX(3,4), XPT(4), YPT(4), ZPT(4), XI1(100), XI2(100)
     3
              ,XI3(1CO),XI4(1CG),ETA1(1CC),ETA2(1CO),ETA3(1OO),ETA4(1OC),
              <u>ZETA1(106),ZETA2(1CC),ZETA3(10C),ZETA4(1CO),XLX(10C),</u>
              XMX(1CC),XNX(1CC),XLE(1CC),XME(1CG),XNE(1CC),XLZ(1CO),
              7
              C3(1CC), C4(1CC), B(1CC, 1C2), SIGX(1CO), SIGZ(1CO), NPTS, NEVCH,
              EPS.AN.BN.GN.AX.BX.GX.AE.BE.GE.CX.CE.CZ.C5.D6.D7.SJ.NFLG.
     ç
              EM1, EM2, EM3, EM4, XPP, YPP, ZPP, YRPP, XIIJ, ETAIJ, ZETAIJ, RU, R1
      <u>.CCMMCN_XIRIJ.ETARIJ.ZETRIJ.TIJ.TRIJ.VXI.VETA.VZETA.TMP1.TMP2.TMP3.</u>
              TMP4,TMP,VX,VY,VZ,AIJ,ARIJ,N1,N2,NPRNT,MPRNT,NIT
      DIMENSICH X(100,4), Y(100,4), Z(100,4), XIK(100,4), ETAY(100,4),
                 ZETAK(1CC,4)
      <u>EGUIVALENCE (x,x1),(Y,Y1),(2,Z1),(XIK,X11),(ETAK,ETA1),(ZETAK,</u>
                   ZETA1)
      DIMENSION LI(10), L2(10)
    1 JS = N1
      EPS1 = 1CC.C.EPS
    2 IT = C
    3 DC 6 I=1.NPTS
U1(I) = C.C
    4 CL 5 J=1. NPTS
      TERM = -8(1,J)/8(1,I)
      IE(I.EC.J) TERM = C.C
      U1(I) = U1(I) + TERM * U1(J)
    5 CENTINUE
      U1(I) = U1(I) + B(I, JS) / P(I, I)
    6 CCATINUE
    7 DC 1C I=1, NPTS
      IF(U2(I).NE.C.C)GC TC 8
      TMP = ABS(L2(I)-L1(I))
      GC TC 9
    8 \text{ TMP} = ABS((L2(I)-L1(I))/L2(I))
    9 IF(TMP.GT.EPS) GC TL 15
   16 CCNTINUE
      IELUS.EC.NZ) CC TC 13
   11 DC 12 I=1, NPTS
      \underline{SIGX(I)} = \underline{LI(I)}
   12 CENTINUE
      15 = VS
      GL IL 2
   13 CC 14 [=1; NPIS
SICZ(I) = L1(I)
   14 CENTINUE
      RETURN
   15 II = II+1
      IF (11.GE.NII) LC 16 18
   16 DL 17 J=1, NPTS
      U2(I) = U1(I)
   17 CCNTINLE
      GC TL 3
   18 IFIJS.EL.NZI CC IL 19
```

A Ash hales !

WRITE(6,1CCC) EPS1, NIT

10CO FERMAT (5X48FECLATIONS FOR SIGMA X DID NOT CONVERGE TO WITHIN F7.4

1 ,12F PER CENT IN 16, 11F ITERATIONS )

GC TU 11

19 WRITE(6,1CC1) EPS1, NIT

10G1 FORMAT( 5X48FECLATIONS FOR SIGMA Z DID NOT CONVERGE TO WITHIN F7.4

1 ,12F PERCENT IN 16, 11F ITERATIONS )

GC TU 13

END

```
$IBFTC ZZGUT
                LIST, REF
      CALCULATION OF POTENTIAL FLOW ABOUT A HELICOPTER FUSELAGE - CUTPUT
      SCEROUTINE CLIPUT
      <u>ccmmcn x1(1cc).x2(1cc).x3(1cc),x4(1cc),</u>Y1(1cc),Y2(1cc),Y3(1cc),
              Y4(100), Z1(100), Z2(100), Z3(100), Z4(100), XBAR(100), YBAR(100)
              .ZBAR(106),AMTX(3,4),XPT(4),YPT(4),ZPT(4),XI1(100),XI2(100)
              ,XI3(100),XI4(100),ETA1(100),ETA2(100),ETA3(100),ETA4(100),
              ZETA1(100), ZETA2(100), ZETA3(100), ZETA4(100), XLX(100),
              XMX(100),XMX(100),XLE(160),XME(130),XME(160),XLZ(100),
              <u> XMZ(1CC),</u>XNZ(1GO),RIJ(4),EIJ(4),HIJ(4),C1(1OU),C2(1GC),
              E3(1001, D4(100), B(100, 102), SIGX(100), SIGZ(100), APTS, NEVCH,
              EFS, AN, BN, GN, AX, BX, GX, AE, BE, GE, CX, CE, CZ, C5, C6, D7, SJ, NFLG,
              EMI, EM2, EM3, EM4, XPP, YPP, ZPP, YRPP, XIIJ, ETAIJ, ZETAIJ, RS, RI
      CCMMCN XIRIJ, ETARIJ, ZETRIJ, TIJ, TRIJ, VXI, VETA, VZETA, TMP1, TMP2, TMP3,
              TMP4, TMP, VX, VY, VZ, AIJ, AKIJ, N1; N2, NPRNI, MPRNT, NIT
      <u>UIMENSICA X(100,4),Y(100,4),Z(100,4),XIK(100,4),ETAK(100,4),</u>
                  2ETAR(100,4)
       ECLIVALENCE (X.XI), (Y.YI), (Z,ZI), (XIK,XII), (ETAK, ETAI), (ZETAK,
                    ZETALL
      PUNCH 1CCC, NPTS
                       HELICCPIER FUSELAGE PROGRAM 16,224 POINTS - HARVEY
 1000 FCRMAT(32FZZ
      1SEL [B, 12X2+ZZ )
       I1 = 1
       12 = 2
       13 = 3
     2 DC 3 I=1, NPTS
       PUNCH 1001, XEAR(I), YEAR(I), ZEAR(I), SIGX(I), SIGZ(I), ZERC, I, II
       PUNCH 1.01, XII(1), XIZ(I), XI3(I), XI4(I), E[A1(I), ETAZ(I), I, IZ
       PUNCH 1001, ETA3(1), ETA4(1), E1(1), C2(1), D3(1), C4(1), 1,13
       PLACE 10-1, XLE(1), XME(1), XAE(1), XLZ(1), XMZ(1), XAZ(1), I, 14
 1001 FCRMAT(6612.5,16,12)
     3 CCNTINUE
       NPAGE = NPTS/5:
       IF (NPAGE +5C.LI.NPIS) NPAGE = NPACE+1
     4 DC 5 IELLAPACE
       I1 = 5C*(I-1)*1
       12 = MINC(11+44+NPT5)
       WRITE (6,1002) (SIG*(J), SIG2(J), XL2(J), XM2(J), XM2(J), J=I1, [2)
. ICC2.ECRMAT(1H1:44×42HPCTENTIAL HLCW APOUT A HELICOPTER FUSELAGE //18×
               THSICMA X, 15×7FSICMA Z, 12×11FLAMBCA ZETA, 14×7HML ZETA, 15×
               7HNU 26TA / (627.5,4822.5) }
     5 CENTINUE
       <u>RETURN</u>
       ENL
```

SUBROUTINE SIMSOL(A,XK,LL) DIMENSION A(LL,LL) C KK- SIZE TO SOLVE , LL 1ST DIMENSION OF A IN MAIN PROGRAM  L=1	\$IBFTC GBSIMS		•
DIMENSION A(LL,LL)   C		219	001
C KK- SIZE TO SÖLVE , LL 1ST DIMENSION OF A IN MAIN PROGRAM C19 003  N=KK C19 004  L=1		• • • •	
N=KK	C KK- SIZE TO SOLVE . LL 1ST DIMENSION DE A IN MAIN PROGRAM	Ċ19	003
L=1			
VI = N + 1			
10 L1=L+1			
IFIL-N)21,21,50			
21 K=0    BIG=0.0    DJ 25 I=L,N    Z=ABS(A(I,L,L))    IF (Z,LE,BIG) GO TO 25    K=1    BIG=Z    Z5 CJNTINUE			
BIG=0.0   DJ 25   I=I,N   C19 010     I		_	
DO 25 I=L,N     Z=ABS(A(I,L))  IF (Z-LE-BIG) GO TO 25  K=I  BIG=Z  25 CONTINUE  C19 014  26 IF (BIG.LE.O.O) CALL DUMP  C DETERMINAVIE O , MO SOLUTION  32 IF(K-L)26,40,35  C19 017  35 DO 37 J=L,NI  B=A(K,J)  A(K,J)=A(L,J)  A(K,J)=A(L,J)  C19 022  A(L,J)=B  C19 021  37 CONTINUE  C19 022  40 DO 41 J=L,NI  C19 022  41 A(L,J)= A(L,J)/A(L,L)  C19 023  41 A(L,J)= A(L,J)/A(L,L)  C19 025  IF(L-N)(A3,50,26  C19 026  43 DO 48 I=L1,N  C19 027  IF(A(I,J))+A(I,J)+A(I,L)  C19 027  IF(A(I,J))+A(I,J)-A(L,J)+A(I,L)  C19 029  45 A(I,J)= A(I,J)-A(L,J)+A(I,L)  C19 020  C19 030  C19 031  C19 034  C19 041  C19 041  C19 041  C19 042  C19 042  C19 042  C19 042  C19 042  C19 042		CI).	007
Z=ABS(A(I,L))         IF (2.LE.BIG) GO TO 25         K=I         BIG=Z         25 CJNTINUE       C19 014         26 IF (BIG_LE.O.0) CALL DUMP       C19 016         32 IFI(K-L)26,40,35       C19 017         35 DJ 37 J=L,VI       C19 018         B=A(K,J)       C19 019         A(K,J)=A(L,J)       C19 020         A(L,J)=B       C19 021         37 CJNTINUE       C19 022         40 DJ 41 J=L1,N1       C19 023         41 A(L,J)= A(L,J)/A(L,L)       C19 024         42 A(L,L)= 1.       C19 025         IF(L-N)43,50,26       C19 026         43 DJ 48 I=L1,N       C19 027         IF(A(I,L))=A(L,J)+A(L,J)+A(I,L)       C19 027         IF(A(I,L))=A(I,J)-A(L,J)+A(I,L)       C19 029         44 DJ 45 J=L1,N1       C19 029         45 A(I,J)=A(I,J)-A(L,J)+A(I,L)       C19 030         L=L1       C19 030         GO TO 10       C19 030         I=I-I       C19 035         51 DO 60 12=1,N2       C19 036         I=I-I       C19 036         I=N-I2       C19 036         I=I-I1       C19 037         D3 59 J=I1,N       C19 036         I=I		C10	010
IF (Z_LE_BIG) GO TO 25   K=1     BIG=2     25 CONTINUE   C19 014     C DETERMINANT= 0 ,MO SOLUTION   C19 016     32 IF(K-L) 26,40,35   C19 017     35 DO 37 J=L,N1   C19 018     B=A(K,J)   C19 019     A(K,J)=A(L,J)   C19 020     A(L,J)=B   C19 021     A(L,J)=B   C19 021     A(L,J)=A(L,J)/A(L,L)   C19 023     A(L,J)=A(L,J)/A(L,L)   C19 023     A(L,J)=A(L,J)/A(L,L)   C19 024     A(L,J)=A(L,J)/A(L,L)   C19 025     A(L,J)=A(L,J)/A(L,L)   C19 026     A(L,J)=A(L,J)/A(L,L)   C19 026     A(L,J)=A(L,J)+A(L,J)/A(L,L)   C19 027     IF(A(I,J))+A(I,J)+A(I,L)   C19 027     A(L,J)=A(I,J)-A(L,J)+A(I,L)   C19 028     A(L,J)=A(I,J)-A(L,J)+A(I,L)   C19 030     A(L,J)=A(I,J)-A(L,J)+A(I,L)   C19 031     A(L,J)=A(I,J)-A(L,J)+A(I,L)   C19 031     A(L,J)=A(I,J)-A(L,J)+A(I,L)   C19 035     A(L,J)=A(I,J)-A(I,J)+A(I,J)+A(J,NI)   C19 036     A(L,J)-A(L,J)-A(L,J)-A(L,J,NI)   C19 036     A(L,J)-A(L,J)-A(L,J,NI)   C19 037     A(L,J)-B(L,J)-A(L,J,NI)   C19 041     A(L,J)-A(L,J,J,NI)   C19 041     A(L,J)-A(L,J,J,NI)   C19 042     A(L,J)-A(L,J,J,NI)   C19 043     A(L,J)-A(L,J,J,NI)   C19 044     A(L,J,J,L)-A(L,J,J,NI)   C19 044     A(L,J,J,L)-A(L,J,J,NI)   C19 045     A(L,J,J,L)-A(L,J,J,NI)   C19 045     A(L,J,L)-A(L,J,J,NI)   C19 045     A(L,J,L)-A(L,J,L,L)-A(L,J,NI)   C19 046     A(L,J,L)-A(L,J,L,L)-A(L,J,NI)   C19 046     A(L,J,L)-A(L,J,L,L)-A(L,J,NI)   C19 046     A(L,J,L)-A(L,J,L,L,L)-A(L,J,NI)   C19 046     A(L,J,L)-A(L,L,L,L)-A(L,J,NI)   C19 046     A(L,J,L)-A(L,J,L,L,L)-A(L,J,NI)   C19 046     A(L,J,L)-A(L,J,L,L,L,L)-A(L,L,L,L,L)-A(L,L,L,L,L,L)     A(L,J,L,L,L,L,L,L,L,L,L,L,L,L,L,L,L,L,L,L		619	OIO
K=I   BIG=Z   C19   O14   C26   IF (BIG.LE.O.O) CALL DUMP   C   DETERMINAYI= 0 , MO SOLUTION   C19   O16   O17   O18   O18   O19   O17   O18   O19			
BIG=Z 25 CONTINUE 26 IF (BIG.LE.O.O) CALL DUMP C DETERMINANT= 0 ,MO SOLUTION  32 IF(K-L)26,40,35 C19 017 35 D3 37 J=L,NI C19 018 B=A(K,J) A(K,J)=A(L,J) A(K,J)=A(L,J) C19 020 A(L,J)=B C19 021 A(L,J)=B C19 022 40 00 41 J=L1,NI C19 023 41 A(L,J)= A(L,J)/A(L,L) C19 025 41 A(L,J)= 1. C19 025 C19 026 43 00 48 I=L1,N C19 027 IF(A(I,J)+4,48,44 C19 027 IF(A(I,J)+4,48,44 C19 028 44 00 45 J=L1,NI C19 027 A5 A(I,J)= A(I,J)- A(L,J)*A(I,L). C19 028 C19 026 C19 027 C19 027 C19 028 C19 026 C19 027 C19 027 C19 028 C19 028 C19 029 C19 029 C19 031 C19 032 C19 035 C19 036 C19 037 C19 036 C19 037 C19 037 C19 038 C19 037 C19 038 C19 039 IF(A(I,J)56,51,51 C19 036 C19 037 II=I+1 C19 038 C19 037 II=I+1 C19 038 C19 037 C19 038 C19 037 II=I+1 C19 038 C19 039 IF(A(I,J)56,59,58 C19 037 II=I+1 C19 038 C19 037 C19 038 C19 039 C19 037 C19 037 C19 038 C19 037 C19 038 C19 037 C19 038 C19 037 C19 038 C19 039 C19 037 C19 038 C19 039 C19 037 C19 038 C19 039 C19 037 C19 038 C19 037 C19 041 C19 042 C19 043 C19 043 C19 043 C19 043 C19 043 C19 044			
25 CONTINUE 26 IF (BIG.LE.O.O) CALL DUMP 27 DETERMINATE O ,MO SOLUTION 38 IF(K-L)26,40,35 39 TJ = L,N1 30 D3 7 J = L,N1 31 B=A(K,J) A(K,J)=A(L,J) A(K,J)=B C19 019 A(L,J)=B C19 021 A(L,J)=B C19 022 A(L,J)=A(L,J)/A(L,L) C19 023 A(L,J)=A(L,J)/A(L,L) C19 024 A(L,L)= 1 C19 025 IF(L-N)43,50,26 C19 025 IF(A(I,L))44,48,44 C19 027 IF(A(I,L))44,48,44 C19 028 A(L,L)=A(L,J)-A(L,J)+A(L,L) C19 029 A(L,L)=A(L,J)-A(L,J)+A(L,L) C19 029 A(L,L)=A(L,J)-A(L,J)+A(L,L) C19 029 A(L,L)=A(L,L)-A(L,L			
26 IF (BIG.LE.O.O) CALL DUMP C DETERMINATE O ,MO SOLUTION  32 IF(K-L) 26, 40, 35 C19 017 35 D3 37 J=L, N1 C19 018 B=A(K,J) A(K,J)=A(L,J) A(L,J)=B C19 020 A(L,J)=B C19 021 37 CONTINUE C19 023 41 A(L,J)= A(L,J)/A(L,L) C19 023 41 A(L,J)= A(L,J)/A(L,L) C19 024 42 A(L,L)= 1 C19 025 IF(L-N) 43,50,26 C19 026 43 D0 48 I=L1,N C19 027 IF(A(I,J) 144,48,44 C19 028 44 D0 45 J=L1,N1 C19 027 A(I,J)= A(I,J)- A(L,J)*A(I,L) C19 028 C19 026 C19 026 C19 026 C19 027 IF(A(I,J) 15,1,51 C19 030 C19 031 IF(N2) 1,51,51 C19 032 I=N-I2			01/
C       DETERMINANT= 0, MO SOLUTION       C19 016         32 IF(K-L)26,40,35       C19 017         35 D3 37 J=L,N1       C19 018         B=A(K,J)       C19 019         A(K,J)=A(L,J)       C19 020         A(L,J)=B       C19 021         37 CONTINUE       C19 022         40 D0 41 J=L1,N1       C19 023         41 A(L,J)= A(L,J)/A(L,L)       C19 025         42 A(L,L)= 1.       C19 025         IF(L-N)43,50,26       C19 026         43 D3 48 I=L1,N       C19 027         IF(A(I,J))44,48,44       C19 027         44 D0 45 J=L1,N1       C19 029         45 A(I,J)= A(I,J)- A(L,J)*A(I,L).       C19 030         L=L1       C19 030         GD TO 10       C19 030         L=L1       C19 035         51 D0 60 I2=I,N2       C19 036         I=N-I2       C19 037         II=I+1       C19 037         D3 59 J=II,N       C19 039         IF(A(I,J))58,59,58       C19 040         58 A(I,NI)= A(I,NI)-A(I,J)*A(J,NI)       C19 041         59 CONTINUE       C19 043         60 CONTINUE       C19 043         61 RETURN       C19 044		619	014
32 IF(K-L)26,40,35 35 DJ 37 J=L,N1 35 DJ 37 J=L,N1 36 A(K,J) = A(L,J) A(K,J) = A(L,J) = A(L,J			01.
35 D3 37 J=L,N1 B=A(K,J) B=A(K,J) A(K,J)=A(L,J) A(L,J)=B C19 020 A(L,J)=B C19 021 37 C3NTINUE C19 022 40 D3 41 J=L1,N1 C19 023 41 A(L,J)= A(L,J)/A(L,L) C19 023 41 A(L,J)= A(L,J)/A(L,L) C19 025 IF(L-N)43,50,26 C19 026 43 D3 48 I=L1,N C19 027 IF(A(I,J))44,48,44 C19 028 44 D3 45 J=L1,N1 C19 029 45 A(I,J)= A(I,J)- A(L,J)+A(I,L). C19 030 C19 031 L=L1 C3 03 D3			
B=A(K,J) A(K,J)=A(L,J) A(K,J)=A(L,J) A(L,J)=B C19 020 A(L,J)=B C19 021 A(L,J)=B C19 022 A(D D 41 J=L1,N1 C19 023 A(L,L)= A(L,J)/A(L,L) C19 025 A(L,L)= 1 C19 025 A(L,L)= 1 C19 025 A(L,L)= 1 C19 027 IF(L-N)43,50,26 C19 026 A3 D 48 I=L1,N C19 027 IF(A(I,L))44,48,44 C19 028 A4 D 45 J=L1,N1 C19 029 A5 A(I,J)=A(I,J)-A(L,J)*A(I,L) C19 030 C19 031 L=L1 G0 TD 10 C19 032 I=L1 IF(N2)51,51,51 C19 035 51 D0 60 I2=1,N2 I=N-I2 I1=I+1 D0 59 J=I1,N C19 036 I=N-I2 I1=I+1 D0 59 J=I1,N C19 038 IF(A(I,J))58,59,58 C19 040 S8 A(I,N1)=A(I,N1)-A(I,J)*A(J,N1) C19 041 C19 042 C0 CONTINUE C19 044 C0 CONTINUE C19 044 C0 CONTINUE C19 044			
A(K,J)=A(L,J)			
A(L,J)=B 37 CONTINUE C19 022 40 D0 41 J=L1,N1 C19 023 41 A(L,J)= A(L,J)/A(L,L) C19 025 42 A(L,L)= 1. C19 025 IF(L-N)43,50,26 C19 026 43 D0 48 I=L1,N C19 027 IF(A(I,J))44,48,44 C19 028 44 D0 45 J=L1,N1 C19 029 45 A(I,J)= A(I,J)- A(L,J)*A(I,L). C19 030 C19 031 C19 032 C19 033 S0 N2=N-1 C19 033 S0 N2=N-1 C19 036 I=N-12 C19 036 I=N-12 C19 037 II=I+1 C19 036 I=N-12 C19 037 II=I+1 C19 038 I=N-12 C19 039 I=(A(I,J))58,59,58 C19 040 S8 A(I,N)= A(I,N)-A(I,J)*A(J,N1) C19 040 C0 CONTINUE C19 044 C0 CONTINUE C19 044 C19 044 C19 044 C19 044 C19 045 C19 046 C			
37 CONTINUE  40 DD 41 J=L1,N1  C19 023  41 A(L,J)= A(L,J)/A(L,L)  C19 025  If(L-N) 43,50,26  C19 026  43 DD 48 I=L1,N  C19 027  IF(A(I,L)) 44,48,44  C19 028  44 DD 45 J=L1,N1  C19 029  45 A(I,J)= A(I,J)- A(L,J)*A(I,L).  C19 030  48 CONTINUE  L=L  GD TD 10  C19 033  50 N2=N-1  IF(N2) 51,51,51  C19 036  I=N-12  I1=I+1  DD 59 J=I1,N  DD 59 J=I1,N  C19 039  IF(A(I,J)) 58,59,58  C19 040  58 A(I,N)= A(I,N)-A(I,J)*A(J,N1)  C19 041  C19 042  C19 044  C19 045  C19 046  C19 047  C19 046  C19 047  C19 046			
40 DD 41 J=L1,N1			
### A(L,J) = A(L,J)/A(L,L) ### C19 025 ### C19 025 ### C19 026 ### C19 026 ### C19 026 ### C19 027 ### C19 027 ### C19 027 ### C19 028 ### C19 027 ### C19 028 ### C19 029 ### C19 030 ### C19 031 ### C19 032 ### C19 032 ### C19 033 ### C19 035 ### C19 035 ### C19 035 ### C19 036 ### C19 046			
42 A(L,L) = 1.     IF(L-N)43,50,26     C19 026 43 00 48 I=L1,N     IF(A(I,L))44,48,44     C19 027     IF(A(I,L))44,48,44     C19 029 45 A(I,J) = A(I,J) - A(L,J) + A(I,L).     C19 031     L=L1     C19 032     C19 032     C19 033     S0 N2=N-1     IF(N2)51,51,51     C19 035     S1 00 60 I2=1,N2     I=N-I2     I=N-I2     I=I+1     D3 59 J=I1,N     I=I+1     D3 59 J=I1,N     I=I+1     S8 A(I,N) = A(I,N) - A(I,J) * A(J,N)     S8 A(I,N) = A(I,N) - A(I,J) * A(J,N)     S9 CONTINUE     C19 042     60 CONTINUE     C19 043     61 RETURN     C19 044			
IF(L-N)43,50,26  43 DD 48 I=L1,N  IF(A(I,L))44,48,44  C19 O28  44 DO 45 J=L1,N1  C19 O29  45 A(I,J)= A(I,J)- A(L,J)*A(I,L).  C19 O30  C19 O31  L=L1  C19 O32  GD TD 10  C19 O33  50 N2=N-1  IF(N2)51,61,51  C19 O35  51 DO 60 I2=1,N2  I=N-I2  II=I+1  DJ 59 J=I1,N  IF(A(I,J))58,59,58  C19 O39  S8 A(I,N1)= A(I,N1)-A(I,J)*A(J,N1)  C19 O41  C19 O42  C19 O42  C19 O43  C19 O44	'41 A(L, L) = A(L, J) / A(L, L)	.¢19_	
43 DD 48 I=L1,N  IF(A(I,L))44,48,44  44 DD 45 J=L1,N1  45 A(I,J)= A(I,J)- A(L,J)*A(I,L).  48 CONTINUE  L=L1  GD TD 10  50 N2*N-1  IF(N2)51,61,51  C19 035  51 DD 60 I2=1,N2  I=N-I2  II=I+1  DD 59 J=I1,N  IF(A(I,J))58,59,58  C19 039  IF(A(I,J))58,59,58  C19 040  C19 042  60 CONTINUE  C19 044			025
IF(A(I,L))44.48.44	· · · · · · · · · · · · · · · · · · ·	C19	026
44 00 45 J=L1,N1  45 A(I,J)= A(I,J)- A(L,J)*A(I,L).  48 CONTINUE  L=L1  GO TO 10  C19 032  50 N2*N-1  IF(N2)51,51,51  C19 035  51 00 60 I2=1,N2  I=N-I2  II=I+1  DO 59 J=I1,N  C19 039  IF(A(I,J))58,59,58  C19 040  S8 A(I,N1)= A(I,N1)-A(I,J)*A(J,N1)  C19 042  60 CONTINUE  61 RETURN  C19 036		C19	
45 A(I,J) = A(I,J) - A(L,J) *A(I,L).  48 CONTINUE  L=L1  GO TO 10  50 N2 = N - 1  IF (N2) 51,51,51  C19 035  51 00 60 I2 = 1,N2  I = N - I2  II = I + 1  DO 59 J = II,N  TF (A(I,J)) 58,59,58  SA A(I,NI) = A(I,NI) - A(I,J) *A(J,NI)  59 CONTINUE  60 CONTINUE  61 RETURN  C19 034  C19 044  C19 044  C19 044			028
48 CONTINUE  L=L1  GO TO 10  C19 032  50 N2=N-1  IF(N2)51,51,51  C19 035  51 00 60 I2=1,N2  I=N-I2  I1=I+1  C19 037  I1=I+1  C19 038  DO 59 J=I1,N  C19 039  IF(A(I,J))58,59,58  C19 040  58 A(I,N1)= A(I,N1)-A(I,J)*A(J,N1)  C19 041  C19 042  60 CONTINUE  C19 044  C19 044		C19	029
48 CONTINUE  L=L1  GO TO 10  C19 032  50 N2=N-1  IF(N2)51,51,51  C19 035  51 00 60 I2=1,N2  I=N-I2  I1=I+1  C19 037  I1=I+1  C19 038  DO 59 J=I1,N  C19 039  IF(A(I,J))58,59,58  C19 040  58 A(I,N1)= A(I,N1)-A(I,J)*A(J,N1)  C19 041  C19 042  60 CONTINUE  C19 044  C19 044	$A(I_{\bullet}J) = A(I_{\bullet}J) - A(I_{\bullet}J) + A(I_{\bullet}I_{\bullet}).$	C19	030
GO TO 10  50 N2*N-1  IF (N2)51,61,51  C19 035  51 00 60 I2=1,N2  I=N-I2  I1=I+1  D0 59 J=I1,N  C19 038  C19 038  C19 039  IF (A(I,J))58,59,58  C19 040  58 A(I,NI) = A(I,NI)-A(I,J)*A(J,NI)  C19 041  C19 042  C19 043  C19 044	48 CONTINUE	C19	031
GO TO 10  50 N2=N-1  IF(N2)51,61,51  C19 035  51 00 60 I2=1,N2  I=N-I2  I1=I+1  C19 036  C19 037  C19 037  C19 038  C19 038  C19 039  IF(A(I,J))58,59,58  C19 040  58 A(I,N1)= A(I,N1)-A(I,J)*A(J,N1)  C19 041  C19 042  C19 043  C19 044  C19 044	L=L1	,C,19,	.032
IF(N2)51,61,51  51 00 60 12=1,N2  I=N-I2  I1=I+1  D0 59 J=I1,N  C19 037  C19 038  C19 038  C19 039  IF(A(I,J))58,59,58  C19 040  S8 A(I,N1)= A(I,N1)-A(I,J)*A(J,N1)  C19 041  C19 042  C19 043  C19 044			033
51 00 60 I2=1,N2 C19 036 I=N-I2 C19 037 I1=I+1 C19 038 D3 59 J=I1,N C19 039 IF(A(I,J))58,59,58 C19 040 58 A(I,N1)= A(I,N1)-A(I,J)*A(J,N1) C19 041 C19 042 C19 043 C19 044	50 N2=N-1	C19	034
51 00 60 I2=1,N2 C19 036 I=N-I2 C19 037 I1=I+1 C19 038 D3 59 J=I1,N C19 039 IF(A(I,J))58,59,58 C19 040 58 A(I,N1)= A(I,N1)-A(I,J)*A(J,N1) C19 041 C19 042 C19 043 C19 044	IF(N2)51,61,51	C19	035
I=N-I2 I1=I+1 C19 038 D0 59 J=I1,N C19 039 IF(A(I,J))58,59,58 C19 040 58 A(I,NI)= A(I,NI)-A(I,J)*A(J,NI) C19 041 C19 042 C19 043 C19 044 C19 044			
Il=I+1	I=N-12		
DO 59 J=11,N	13 m T ± 1		
IF(A(1,J))58,59,58  58 A(1,N1) = A(1,N1)-A(1,J)*A(J,N1)  59 CONTINUE  60 CONTINUE  61 RETURN  C19 043  C19 044			
58 A(I,N1) = A(I,N1)-A(I,J)*A(J,N1)  59 CONTINUE  60 CONTINUE  61 RETURN  C19 041  C19 042  C19 043  C19 044			
59 CONTINUE C19 042 60 CONTINUE C19 043 61 RETURN C19 044			
60 CONTINUE C19 043 61 RETURN C19 044	50 CONTINUE		
61_RETURN C19_044			

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13. ABSTRACT

and the computational results.

This report describes two digital computer programs which direct the calculation of the time-varying flow in the vicinity of a helicopter rotor in forward or hovering flight. Fuselage interference effects are taken into account. The applicability of these programs to specific problems and procedures for their use are the subjects treated here.

First, the assumptions made in constructing the mathematical model and the relationship of the model to the physical flow are outlined. In this connection, the assumptions necessary for numerical analysis and the functional structure of the programs are also given.

Then, the formulations which were coded are presented. Included in the formulations are the coordinate identifications used and the definitions of program variables.

Finally, the procedures for implementation of the programs are given. The relationship of input quantities to aircraft flight parameters, program accuracy and computer running time are specified. A sample calculation, including both inputs and outputs, is presented. Program listings and operational information related to the programs are given in appendices.

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Security Classification

14. KEY WORDS	LIN	LINK A		LINK B		LINK C	
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Helicopter Rotor Rotor Flow Field Aerodynamics Fluid dynamics Digital Computation							

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